## USING CIRCLE COVERING TO TACKLE NESTING REPRESENTATIONS LIMITATIONS

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Motivation

## Cutting and Packing Problem

Efficient cutting of raw material in small pieces is a complex and important task

Strong impact in industrial production costs (energy, raw material savings, environmental benefits)


## Cutting and Packing Problem

$\square$ Aims to find a good fit to minimize wasted space
$\square$ Hard combinatorial and geometric problem
$\square$ Pieces are cut from, or placed inside a set of larger bins, in a non-overlapping configuration
$\square$ If pieces have irregular outlines it is defined as a Nesting problem

## Nesting Problem

$\square$ Also known as Irregular Shapes Placement Problem
$\square$ Characteristics:

- 2D problem
$\square$ One big item, may have defects
$\square$ High number of pieces to place
$\square$ Great diversity on the size of the pieces
$\square$ No overlap between pieces
$\square$ Complex shapes (multi-connected regions, curves, ...)
$\square$ Continuous and/or discrete admissible orientations


## Industrial Applications




## Main Challenges

## Nesting Challenges

$\square$ Obtain adequate representations for the nesting problem
$\square$ Achieve faster and more efficient solutions
$\square$ Efficiently represent the relative positions between pieces

## Geometrical Challenges

$\square$ Efficiently represent non-rectilinear outlines
$\square$ Deal with free rotations

$\sum$
Lack of solutions limit geometric tools
Other problems with similar challenges (ex. collision detection in games/physics engine based simulations)

Geometrical Representations

## Discrete Representations

## Grid

Representation through discretization of geometrical outline (Bin/ Pieces)
$\square$ How is it used?

- Pieces coded into a matrix, $0=$ empty, $1=$ non-empty
- Overlap verification done though analysis of anch dicrratimad alamant
- Pieces are placed on a discretized bin
- if (element $>=1$ ) then Overlap!!
$\square$ Advantages / disadvantages:
- Easy to check feasibility of layout
- Only $90^{\circ}$ rotations
- Can represent any outline

Approximation errors (curves, non-orthogonal segments)

Adequate for integer sized elements \& orthogonal orientations

## Discrete Representations

## Quad-Tree

Tree data structure where each node has 4 children, used to organize and access spatial information
$\square$ How is it used?
$\square$ Irregular outlines are decomposed in non-uniform elements
$\square$ When an element is both empty and $n$
$\square$ Advantages / disadvantages:
$\square$ Very fast searches (overlap)
$\square$ Allows dynamic discretization

- Less memory consumption
$\square$ Similar to grids



## Polygonal Representations

## Polygons

Closed circuit of straight segments
$\square$ How is it used?

- Shape is represented through straight segments
- Bounding boxes are used for initial overlap detection
- D-functions used for direct polygonal comparison
$\square$ Advantages / disadvantages:
$\square$ Overlap detection computationally expensive

- Rotations possible but not efficient

- Numerical precision problems
- Curves approximated by straight lines, tangent to the curve
- Approximation error is controlled



## Polygonal Representations

## No-Fit-Polygon

Points traced by a reference point from an orbital piece, with fixed orientation, while sliding along the external contour of a static piece
$\square$ How is it used?

- Compares a vertex with a polygon
- If (vertex inside of polygon) then Overlap!
$\square$ Advantages / disadvantages:
- Allows faster overlap detection
- Numerical precision problems
- Rotations are computationally expensive
- Discrete rotations
- Pre-computation


## Circle Covering Representations

## Circle Covering

Set of identical/non-identical circles that fully or partially cover an irregular outline
$\square$ How is it used?

- Pieces are replaced by sets of circles
- Mathematical models only for identical circles
$\square$ Overlap detection $\rightarrow$ distance between circles

- If ( $\mathbf{R}_{\mathbf{1}}+\mathbf{R}_{\mathbf{2}}<\mathrm{D}_{1,2}$ ) then Overlap!
$\square$ Advantages / disadvantages:
$\square$ Overlap detection is simple and fast
- Needs circle positioning method
- Continuous rotations are trivial
- Numerical precision problems



## Phi-Functions

## Phi-Functions

Mathematical expression that represents all mutual positions between two objects
$\square$ How is it used?

- The function returns a value
- If (value is negative) then Overlap!
$\square$ Advantages / disadvantages:
- Complex objects are decomposed into basic shapes:



Convex polygons $K$


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- All basic elements have as their primitives:
- Circles, triangle, rectangle, regular and other convex polygons, and their complements
- Shapes represented by unions and intersections of functions

Circle Covering Approach

## Circle Covering Approach

$\square$ Collision detection with circles:

- Games and Physical Engine Based Simulations
- Computation speed is priority
- Approximation error secondary
- Fixed sets of shapes $\rightarrow$ Circles are manually placed
- Nesting
- Higher precision (smaller approximation error)
- Involves much contact between pieces
- Variable sets of shapes $\rightarrow$ Manual placement not viable
- Good automatic method is needed
$\square$ How to position the circles?
$\square$ How to deal with the tradeoff:
$\square$ Number of circles
- Approximation error

Automatic Circle Covering
Method

## Medial Axis

## Topological Skeleton

- Set of all points having more than one closest point on the objects boundary
- Any circle, with its center placed on the skeleton, will always be the biggest circle inside it
$\square$ How is it used?
- Defines the equidistant axis to the outline of the shape
$\square$ The biggest circles can be placed on the skeleton
$\square$ Advantages / disadvantages:
- Reduces complexity of circle placement problem
$\square$ Numerical precision problems



## Medial Axis Construction

$\square$ How is it constructed?
$\square$ Bissection from every pair of sequential segments are intersected, creating a new spawn point, that is the base for a new bissection

- Iteratively repeat previous step, until no more bissections remain
$\square$ Bissection types:
$\square$ Two straight edges
$\square$ Straight edge + vertex
- Two vertexes
$\square$ Convex outline
$\square$ Irregular outline

Straight bissection
Arc of parabola
Straight bissection


## Circle Covering Construction



## Circle Covering Approach

$\square$ How is the approximation controlled?
$\square$ Error is controled by a threshold, which regulates the approximation to the shape outline

$\square$ Lower threshold $=$ better approximation $=$ less error $=$ more circles


## Current Results



| Threshold | Circles | Area (\%) |
| :---: | :---: | :---: |
| 0,75 | 6 | 81,4 |
| 0,50 | 9 | 88,1 |
| 0,25 | 12 | 92,4 |
| 0,15 | 16 | 94,7 |
| 0,10 | 19 | 95,8 |
| 0,05 | 24 | 96,9 |
| 0,01 | 30 | 97,6 |

## Current Results



| Threshold | Circles | Area (\%) |
| :---: | :---: | :---: |
| 10 | 37 | 95,4 |
| 5 | 46 | 96,9 |
| 2 | 66 | 97,9 |
| 1 | 75 | 98,3 |
| 0,5 | 87 | 98,1 |


$\% \quad$ Area coverage

## Other Shapes



## Improvements



| Threshold \% | Circles | Area (\%) |
| :---: | :---: | :---: |
| $20 \%$ | 52 | 85,4 |
| $10 \%$ | 133 | 92,2 |
| $5 \%$ | 299 | 96,1 |
| $2 \%$ | 594 | 98,1 |



| Threshold | Circles | Area (\%) |
| :---: | :---: | :---: |
| 25 | 15 | 97,1 |
| 2 | 24 | 98,2 |

## Improvements



| Threshold \% | Circles | Area (\%) |
| :---: | :---: | :---: |
| $20 \%$ | 124 | 81,1 |
| $10 \%$ | 351 | 92,3 |
| $5 \%$ | 554 | 95,5 |
| $2 \%$ | 1029 | 98,2 |


| Threshold | Circles | Area (\%) |
| :---: | :---: | :---: |
| 10 | 37 | 95,4 |
| 2 | 66 | 97,9 |

## Final Remarks

$\square$ Substantial improvement over previous hierarchical method
$\square$ Circle covering with medial axis useful for polygon representation
$\square$ Numerical precision problems cause many difficulties

## Future Work

$\square$ Increase reliability to numerical errors
$\square$ Expand to deal with holes
$\square$ Support geometric outlines with curves
$\square$ Compare with other C.D. approaches

