

008 **Abstract**

009 Motivated by a breast cancer application, in this work we address a new  
 010 learning task, in-between classification and semi-supervised classifica-  
 011 tion. Each example is described using two different feature sets, not nec-  
 012 essarily both observed for a given example. If a single view is observed,  
 013 then the class is only due to that feature set; if both views are present the  
 014 observed class label is the maximum of the two values corresponding to  
 015 the individual views.

016 We propose new learning methodologies adapted to this learning para-  
 017 digm and experimentally compare them with baseline methods from the  
 018 conventional supervised and unsupervised settings. The experimental re-  
 019 sults verify the usefulness of the proposed approaches.

020 **1 Introduction**

021 According to the World Health Organization, breast cancer was respon-  
 022 sible for approximately 519 000 deaths in 2004 comprising 16% of all  
 023 cancer incidence among women. X-ray mammography is currently con-  
 024 sidered the best imaging method for breast cancer screening and the most  
 025 effective tool for early detection of this disease.

026 In order to standardize the terminology of the mammographic report,  
 027 mammography findings are classified into the BI-RADS scale. Based on  
 028 level of suspicion, lesions can be placed into one of six BI-RADS scores:  
 029 score 0 when the exam is not conclusive, score 1 for no findings, score 2  
 030 for benign findings, score 3 for probably benign findings, score 4 for sus-  
 031 picious findings, score 5 when there is a big probability of malignancy,  
 032 and score 6 for proved cancer. **When more than one finding is present  
 033 in the mammogram, the overall BI-RADS in the medical report cor-  
 034 responds to the finding with highest BI-RADS.** This is the key obser-  
 035 vation that motivates this work.

036 An approach based on standard classification techniques would ex-  
 037 tract features from calcifications and masses, when present, and design a  
 038 classifier in the joint space. One disadvantage of this approach is that it  
 039 is not clear how to use the cases with masses only or calcifications only  
 040 in the design of the classifier nor how to use the classifier in such cases.  
 041 Moreover, the classifier would have to learn automatically from the data  
 042 that the final classification is the maximum of the values obtained from  
 043 the two ‘views’, masses and calcifications; it would thus be better to in-  
 044 corporate this knowledge in the learning process.

045 A second standard option is to train a classifier to make the prediction  
 046 for one type of findings (e.g. masses) and a second classifier for the other  
 047 type of findings (e.g. calcifications); the final classification would be the  
 048 maximum of the two predicted values. To train each individual classi-  
 049 fier, one could use the cases with that finding only, for which one knows  
 050 the true class. The training could be improved by using semi-supervised  
 051 learning techniques: the cases with both findings would be used as un-  
 052 labeled data to improve the performance of the individual classifier. The  
 053 disadvantage of this approach is that, by ignoring the classification when  
 054 both findings are present, one is not using all the information available  
 055 during training: although when both findings are present one does not  
 056 know which one is responsible by the score, one does know that at least  
 057 one of them motivated that score.

058 Motivated by the described application, we formalize a new learning  
 059 paradigm and propose new learning methodologies to make efficient use  
 060 of all the available information.

058 **2 Max-coupling Semi-Supervised Learning**

060 Consider a training set comprising three different type of observations:

- 061 1.  $S_1 = \{\mathbf{x}_i, y_i = f(\mathbf{x}_i)\}$ , where  $i = 1, \dots, N_1$  and  $\mathbf{x}_i \in \mathcal{R}^{d_1}$ , with  $d_1$  the  
 062 dimension of the feature space and  $f(\cdot)$  is unknown.

2.  $S_2 = \{\mathbf{z}_i, y_i = g(\mathbf{z}_i)\}$ , where  $i = 1, \dots, N_2$  and  $\mathbf{z}_i \in \mathcal{R}^{d_2}$ , with  $d_2$  the  
 dimension of the feature space and  $g(\cdot)$  is unknown.
3.  $S_{12} = \{\mathbf{x}_i, \mathbf{z}_i, y_i\}$ , where  $i = 1, \dots, N_{12}$ ,  $\mathbf{x}_i \in \mathcal{R}^{d_1}$  and  $\mathbf{z}_i \in \mathcal{R}^{d_2}$ . It  
 is known that  $y_i = \max(f(\mathbf{x}_i), g(\mathbf{z}_i))$  but  $f(\mathbf{x}_i)$  and  $g(\mathbf{z}_i)$  are both  
 unobserved.

For every observation,  $y_i$  corresponds to a known classification in one of  
 $K$  ordinal classes.

03 **Learning the Max-coupling dependencies**03.1 **A Modified semi-supervised approach**

Self-training first learns a separate classifier for each view ( $\mathbf{x}$  and  $\mathbf{z}$ ) using  
 any labeled examples. The most confident predictions of each classifier  
 on the unlabeled data are then used to iteratively construct additional la-  
 beled training data. Our first proposal to make use of all the available in-  
 formation is inspired on self-training. Two classifiers are initially trained  
 with the samples  $\{\mathbf{x}_i, f(\mathbf{x}_i)\}$ , where  $i = 1, \dots, N_1$  and  $\{\mathbf{z}_i, g(\mathbf{z}_i)\}$ , where  
 $i = 1, \dots, N_2$ , respectively. The two classifiers are used to make predic-  
 tion in the subset  $S_{12}$ . If the maximum of the two predictions agree with  
 the known label, the labeled training point is added only to the classifier  
 predicting the maximum value (in case of a tie, both models receive the  
 new training data). Intuitively, instead of selecting the new training points  
 based on the estimated confidence, the points are chosen if the final pre-  
 dictions agrees with the known label.

03.2 **A Modified on-line supervised approach**

On-line supervised learning algorithms incrementally build the model and  
 dynamically refine it over time using the most recent observation. Denot-  
 ing by  $\mathbf{w}$  the set of parameters of the model, a typical update rule follows  
 the format

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \frac{\partial \mathcal{L}}{\partial \mathbf{w}} \Big|_t,$$

where  $\eta$  is the learning rate and  $\mathcal{L}$  some loss function. We are assum-  
 ing an update rule based on the gradient but similar rules exist for other  
 rationale.

We propose to incorporate in the architecture of the model the knowl-  
 edge about the output, namely that it is the maximum of two independent  
 values; adapting the architecture to the learning problem, we then update  
 the parameters using the aforementioned update rule. We propose to de-  
 sign the global model as the parallel of two individual models coupled  
 by a max computation in the end. Each of the individual models is pa-  
 rameterized by its own set of parameters,  $\mathbf{w}_1$  and  $\mathbf{w}_2$ . Consider now that  
 we receive the current observation and we want to update the join model.  
 When both  $\mathbf{x}_i$  and  $\mathbf{z}_i$  are present, three different cases should be consid-  
 ered:

1.  $\hat{y}_i = \hat{f}(\mathbf{x}_i) \wedge \hat{y}_i > \hat{g}(\mathbf{z}_i)$

Assuming that both models are continuous functions of the param-  
 eters (and the magnitude of the gradient is bounded), then ‘small’  
 changes in the parameters of the second model will not affect the  
 output of the joint model nor the loss function. Therefore, the  
 derivative of the loss in respect to the parameters of the second  
 model is zero and only the first models needs to be updated. Since  
 the loss function at the output of the first model equals the loss at  
 the output of the joint model, the update follows the conventional  
 rule, as if observing the output  $\hat{y}_i$  in the output of the first model.

2.  $\hat{y}_i = \hat{g}(\mathbf{z}_i) \wedge \hat{y}_i > \hat{f}(\mathbf{x}_i)$

In this case the roles of the first and second models are reversed,  
 and one only needs to conventionally update the second model.

single view percentage	Dataset	Standard Two Classifiers	Standard One Classifier	Standard tri-Training	proposed semi-supervised	proposed batch
40%	ESL vs ESL	47(49/45)%	28(23/34)%	14(15/11)%	10(11/9)%	8(8/7)%
	ESL vs bcct	39(40/18)%	21(20/50)%	15(16/11)%	9(9/5)%	7(8/5)%
	ESL vs Pasture	18(11/41)%	20(13/45)%	11(10/13)%	5(3/10)%	3(2/6)%
	bcct vs bcct	32(36/27)%	24(21/27)%	13(14/11)%	15(18/11)%	9(10/7)%
	bcct vs Pasture	4(4/27)%	2(2/18)%	8(7/17)%	1(1/5)%	1(1/2)%
	Pasture vs Pasture	18(17/18)%	7(5/10)%	11(11/12)%	3(4/3)%	3(4/3)%
Time elapsed (sec)		6.52	12.47	714.18	780.82	884.22

Table 1: Overall MAE results for real datasets with 50% data for training. Results for are present in the format ‘complete test set (single view/two views)’.

3.  $\hat{\mathbf{y}}_i = \hat{g}(\mathbf{z}_i) = \hat{f}(\mathbf{x}_i)$  In this case both models should be updated, as if observing the output  $\hat{y}_i$  in the output of each of the models. This follows from the observation that

$$\frac{\partial \mathcal{L}(y_i, \hat{y}_i)}{\partial \mathbf{w}_1} = \frac{\partial \mathcal{L}(y_i, \hat{f}(\mathbf{x}_i))}{\partial \mathbf{w}_1}$$

and

$$\frac{\partial \mathcal{L}(y_i, \hat{y}_i)}{\partial \mathbf{w}_2} = \frac{\partial \mathcal{L}(y_i, \hat{g}(\mathbf{z}_i))}{\partial \mathbf{w}_2},$$

where  $\mathbf{w}_1$  and  $\mathbf{w}_2$  represent the vector of parameters for the first and second models, respectively.

When only one of  $\mathbf{x}_i$  and  $\mathbf{z}_i$  is present only the corresponding model is updated.

### 3.3 A Modified batch supervised learning approach

The on-line proposed model suggests that the most informative observations are the ones currently being misclassified, since these are the ones leading to an update of the models. This paves the way to a new batch mode supervised learning: instead of adding to the current training set the points where both classifiers agree (as in the standard co-training) or the set of points where the maximum of the two outputs agrees with the observed global classification, every point will be used, either in the training set of model 1 or in the training set of model 2 (or in both).

The algorithm consists thus in first training two models, one with  $S_1$  and another with  $S_2$ . Each model will be used to predict the class of the samples in  $S_{12}$ . Each model is then iteratively retrained with the original samples plus all the samples from  $S_{12}$  for which the model prediction was higher. For example, if for the first sample in  $S_{12}$ , model A predicts a higher class than model B, that sample will be added to the training set of model A.

It is important to highlight a key difference to the proposed model based in semi-supervised learning techniques. With the semi-supervised based model, only examples where the final prediction agrees with the known label are incorporated in the training set of one or both models; moreover when an example is added in one of the training sets it is no longer removed. With the now proposed approach, all examples are selected to integrate one or both training sets; between two epochs examples can be moved from one training set to the other.

## 4 Experimental Validation

### 4.1 Datasets

In our previous work [2], experiments with synthetic datasets were presented. Here, three types of real data were used and combined. The first dataset, ESL, contains 488 profiles of applicants for certain industrial jobs. The class assigned to each applicant was an overall score corresponding to the degree of fitness for the type of job. bcct dataset, encompasses on 960 observation taken from [1] and expresses the aesthetic evaluation of Breast Cancer Conservative Treatment (BCCT). The aesthetic outcome of the treatment for each and every patient was classified in one of the four categories: Excellent, Good, Fair and Poor. The last dataset, Pasture, contains information on the pasture production from a variety of biophysical factors. The target feature has been categorized in three classes, (Low, Medium, High), evenly distributed in the dataset of 36 instances. Each one of the above three datasets was considered as one of the views, yielding a total of 6 datasets.

## 4.2 Methodology

We randomly split the datasets into training and test sets. In order to study the effect of varying the size of the training set, we considered two possibilities: 10% and 50% of all the data used for training. Since the data is ordinal, we adopted the MAE as a measure of performance. Each model parameterization was optimized by cross-validation inside the training set.

All models were instantiated with SVMs. The standard two classifiers model trains a classifier for each of the views, ignoring the subset  $S_{12}$  for training. The standard one classifier model trains a single classifier in the complete dataset, previously replacing unknown feature-values by the corresponding average value.

As standard semi-supervised technique, Tri-training [3] was selected. In this method, the labeled data are split in three sets and a classifier is trained in each set. If two of them agree on the classification of an unlabeled point, the classification is used to ‘teach’ the other classifier.

## 4.3 Results

Overall results are presented in Table 1. Besides the MAE in the complete test set, we also show the performance for the test subset with information only for a single view and for the subset with the two views.

Since the results for 10% and 50% of the data for training were consistent in terms of relative performance, we only show results for the last percentage.

A first conclusion is that the standard two classifiers model was the worst performing model. The single classifier approach has also difficulties learning from the data. The proposed batch model is the best-performing model both in the complete test set and in the subset comprising only single-view examples.

So far, we are still collecting our database of mammograms and manually annotating them and therefore we are unable to present results for this specific application. Nevertheless, the results obtained for the presented data are very promising and potentially interesting for different scenarios.

## 5 Conclusion

In this paper we propose a new learning paradigm, in between classification and semi-supervised classification. In proposed max-coupled setting, for every observation, we do possess some information about the label; however, in a subset of the examples, the knowledge is incomplete, corresponding to the worst-case classification of the individual views of the example. The quality of our results motivate us to further pursue the problem. An interesting question, which we plan to research in the future, is if the design ‘from scratch’ of models with embedded knowledge of the max-coupled setting can further improve the results. We will also conduct a larger validation of these ideas on real datasets.

## References

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