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Abstract	In this paper, the main planning problems of deterministic base mo key features of food are organized around t objective functions an dates, customers' beha dependent demand. T we solve an illustra and analyze the chan plan. The differences choosing a model sui to accommodate the Moreover, acknowled evaluating the amount in lowering overall cos the deterministic base	complexities related to the modeling of production f food products are addressed. We start with a del and build a road-map on how to incorporate production planning. The different "ingredients" he model components to be extended: constraints, nd parameters. We cover issues such as expiry avior, discarding costs, value of freshness and age- to understand the impact of these "ingredients", tive example with each corresponding model ges on the solution structure of the production a across the solutions show the importance of table to the particular business setting, in order multiple challenges present in these industries. Iging the perishable nature of the products and and quality of information at hands may be crucial ats and achieving higher service levels. Afterwards, e model is extended to deal with an uncertain d risk management issues are discussed using a		



similar illustrative example. Results indicate the increased importance of risk-management in the production planning of perishable food goods.

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Abstract In this paper, the main complexities related to the modeling of production 4 planning problems of food products are addressed. We start with a deterministic base 5 model and build a road-map on how to incorporate key features of food production 6 planning. The different "ingredients" are organized around the model components to 7 be extended: constraints, objective functions and parameters. We cover issues such 8 as expiry dates, customers' behavior, discarding costs, value of freshness and age- 9 dependent demand. To understand the impact of these "ingredients", we solve an 10 illustrative example with each corresponding model and analyze the changes on the 11 solution structure of the production plan. The differences across the solutions show 12 the importance of choosing a model suitable to the particular business setting, in 13 order to accommodate the multiple challenges present in these industries. Moreover, 14 acknowledging the perishable nature of the products and evaluating the amount 15 and quality of information at hands may be crucial in lowering overall costs 16 and achieving higher service levels. Afterwards, the deterministic base model is 17 extended to deal with an uncertain demand parameter and risk management issues 18 are discussed using a similar illustrative example. Results indicate the increased 19 importance of risk-management in the production planning of perishable food 20 goods. 21

1 Introduction

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The supply chain planning of food products is ruled by the dynamic nature of its ²³ products. Throughout the planning horizon, the characteristics of these products go ²⁴ through significant changes. The root cause for these changes may be related to, for ²⁵ example, the physical nature of the products or the value that the customer lends ²⁶ to them. Without acknowledging the perishable nature of food products, one may ²⁷ incur in avoidable spoilage costs (for example, in the case of meat products) or, ²⁸ on the other hand, sell the product before it is close enough to its best state (for ²⁹

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example, in the case of cheese products). In this paper, we focus on perishable food 30 products that start worsening their properties after being produced. 31

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Fleischmann et al. [7] define planning as the activity that supports decisionmaking by identifying the potential alternatives and making the best decisions 33 according to the objective of the planners. Let us look into the specific challenges 34 of engaging in a production planning activity in the context of food products. 35

In order to identify the alternatives it is important to frame the decisions that the 36 decision maker wants to make. It is common to organize the supply chain planning 37 according to two dimensions: the supply chain process (procurement, production, 38 distribution and sales) and the hierarchical level (strategic, tactical and operational). 39 The scope of this paper is in the production supply chain process and we deal 40 with problems arising at the tactical/operational decision level. Therefore, we will 41 address food production planning problems that have to decide about the size of the 42 lots to be produced and about the schedule of these production lots. In this problem, 43 we usually determine the size of lots to be produced while trading off the changeover 44 and stock holding costs. In food production, expiry dates may enforce constraints 45 related to the upper bounds on lot-sizes and consequently the need of scheduling 46 more often a given family of products (increasing the difficulty of sequencing). 47 Expiry dates relate to the concept of perishability that is defined by Amorim et al. 48 [4] as: "A good, which can be a raw material, an intermediate product or a final 49 one, is called 'perishable' if during the considered planning period at least one of 50 the following conditions takes place: (1) its physical status worsens noticeably (e.g. 51 by spoilage, decay or depletion), and/or (2) its value decreases in the perception of 52 a(n internal or external) customer, and/or (3) there is a danger of a future reduced 53 functionality in some authority's opinion.". In this paper, we will consider goods that 54 suffer a physical deterioration, for which customers' attribute a decreasing value and 55 for which authorities usually limit the commercialization period. 56

The second part of Fleischmann et al. [7] definition of planning relates to the ⁵⁷ objectives of the planners. The literature in production planning tackles most of the ⁵⁸ problems with traditional single objective models. The goal is usually related either ⁵⁹ to an operational measure, such as makespan, or to some monetary measure, such ⁶⁰ as cost or profit. In this paper, we show the interest of extending these objectives ⁶¹ by including factors related to the food industry, such as spoilage costs. Moreover, ⁶² the use of a multi-objective approach is described in order to account for the ⁶³ customer willingness for fresher products and to induce a risk conscious strat-⁶⁴ egy. Acknowledging freshness in production planning besides avoiding products' ⁶⁵ spoilage, may yield a substantial intangible gain derived from delivering fresher ⁶⁶ products to customers. Such considerations are closely related to the consumer ⁶⁷ purchasing behavior of perishable goods that should be the concern of any planner ⁶⁸ in a (food) company with a market orientation.

The key contribution of this paper is to provide a systematic approach to a 70 problem that has been tackled sparsely in the literature. We believe that this road-71 map on mixed-integer models for production planning of perishable food products 72 may be useful to any researcher or practitioner willing to start solving a problem 73 in this field. For an extensive review in production planning problems dealing 74



with perishability the readers are referred to Pahl and Voß [9] and for a more 75 comprehensive review on supply chain planning problems dealing with perishability 76 the readers are referred to Amorim et al. [4].

In the remainder of the paper, we present how a traditional base model dealing 78 with the production planning of food products has to be changed in order to 79 accommodate the characteristics of the products it has to deal with. Therefore, we 80 start by presenting a deterministic base model in Sect. 2. In Sect. 3, we understand 81 how the constraints have to be extended to incorporate key aspects, such as the 82 fact that products have a limited shelf-life or that customers pick up the fresher 83 available products. Section 4 analyses the possible changes in the objective function: 84 discarding costs of perished goods and valuing in a different objective function 85 the freshness. Section 5 tackles the possibility of having more information on 86 key parameters - dependency between price and age and between demand and 87 age. The "ingredients" presented throughout these section can be mixed together 88 in various ways to form the "recipe" suitable for the production environment. In 89 order to help understanding the implications of these "ingredients" in the solution 90 structure, all models are solved for an illustrative example in Sect. 6. Section 7 91 discusses the extension of the deterministic base model to a stochastic setting in 92 which demand or other parameters may be uncertain leading the notion of a risk- 93 conscious planning. This model road-map is summarized in Fig. 1. Finally, in Sect. 8 94 the main conclusions are presented. 95



Fig. 1 Road-map of the different "ingredients" presented in this paper



2 Base Model

We start by presenting a base model for production planning in food industries. This 97 model focuses on the packaging stage and has no considerations about the perishable 98 nature of the products. 99

One important concept in the fast moving consumer food goods is the recipe. 100 Usually, products belong to a certain recipe that requires a major setup and the 101 products within the recipes just need a minor setup. This is known as production 102 wheel policy by practitioners. We use an adaptation of the block planning formula- 103 tion [8] that was designed for similar production environments to that of the food 104 industry. To make it clearer, a block corresponds to a recipe and within and between 105 recipes the sequence of products is set a priori. Therefore, the only decision to be 106 made for each block/product, besides the sizing of the lots, is whether to produce 107 it or not. This modeling approach increases the application potential of decision 108 support systems in production planning, because decision makers are comfortable 109 with the definition of the recipes and, simultaneously, the scheduling complexity 110 is fairly reduced increasing the computational tractability of the related problems. 111 In Fig. 2 a production schedule with two blocks, A and B, is depicted. Notice that 112 before producing products of a given recipe a major setup is necessary. Afterwards, 113 all products within the same recipe are produced after doing a minor setup. Block 114 A has usually a lighter color or a less intense flavor than block B. Examples of this 115 recipe structure can be found in the yoghurt, milk, juice and chocolate industries. 116

Let us now move to a formal description of the problem. Consider a set of 117 products $k = 1, \dots, K$ that are produced based on a certain recipe/block j = 118 $1, \ldots, N$. There is only one recipe to produce each product and, therefore, a product 119 is assigned to one block only. Hence, for each block j there is a set $\mathcal{K}_{\mathscr{I}}$ of 120 products k related to it. Blocks are to be scheduled on $l = 1, \ldots, L$ parallel 121 production lines over a finite planning horizon consisting of periods $t = 1, \ldots, T_{122}$ with a given length. This length is related to the company's practice of measuring 123 external elements, such as demand or perishability (thus, periods correspond to 124 days, weeks or months in most of the tactical/operational cases). According to 125 the block structure, all scheduling decisions are already made for both recipes and 126 products. Hence, the production sequence is determined beforehand, minimizing 127 the setup times and costs according to the planner expertise [8]. This is particularly 128 useful in practice, since companies have difficulties in measuring setups costs and 129 setups times accurately. This limitation may reduce the applicability of traditional 130 production planning objective functions. 131

Consider the following indices, parameters, and decision variables that are used 132 hereafter. 133



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Production Planning of Perishable Food Products by Mixed-Integer Programming

Indices	
$l\in \mathscr{L}$	parallel production lines
$j \in \mathcal{N}$	blocks
$k\in \mathscr{K}_{\mathscr{J}}$	products
$t \in \mathscr{T}$	periods
$a \in \mathscr{A} = \{a \in \mathbb{Z}_0^+, t \in \mathscr{T} a \le t\}$	- 1}age (in periods)

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Parameters

C_{lt}	capacity (time) of production line <i>l</i> available in period <i>t</i>	
e_{lk}	capacity consumption (time) needed to produce one unit of product k on line l	
C_{lk}	production costs of product k (per unit) on line l	
u_k	shelf-life of product k just after production (time)	
p_k	price of product k	135
h_k	inventory carrying cost of product k	
m_{lj}	minimum lot size (units) of block <i>j</i> on line <i>l</i>	
$\bar{s}_{li}(\bar{\tau}_{li})$	setup cost (time) of a changeover to block j on line l	
$\underline{s}_{lk}(\underline{\tau}_{lk})$	setup cost (time) of a changeover to product k on line l	
d_{kt}	demand for product k in period t (units)	

Decision Variables

$ \rho_{kt}^a \ge 0 $	initial inventory of product k with age a available at	
	period t	
$\psi^a_{kt} \ge 0$	fraction of the maximum demand for product k	
	delivered with age a at period t	
$q_{lkt} \ge 0$	quantity of product k produced in period t on line l	136
$p_{lkt} \in \{0, 1\}$	equals 1, if line <i>l</i> is set up for product <i>k</i> in period <i>t</i> (0	
C	otherwise)	
$y_{ljt} \in \{0,1\}$	equals 1, if line l is set up for block j in period t (0	
	otherwise)	

From the decision variables it is noticeable that we use an adaptation of 137 the simple plant location (SPL) reformulation to model inventory and demand 138 fulfillment decision variables. In the traditional SPL reformulation [6], it is known 139 for which period the production of a given period refers to. In a food production 140 planning context we are more interested in tracing the actual age of the product. 141 Therefore, in this case, we know for each period the age of the inventory of a given 142 product. This will be rather helpful in limiting the usage of stock based on the shelf-143 life of the products. Moreover, it can also be used to keep track of the freshness of 144 the products delivered to the clients. These potentialities will be further explored in 145 the next sections. Figure 3 shows how traditional decision variables for production 146 quantities (q_{lkt}) are transformed through the adapted SPL reformulation. Basically, 147



Fig. 3 Schematic representation of the adaptation of the simple plant location reformulation with an emphasis on the inventory age

the products produced in a given period correspond to the inventory with age 0 148 (ρ_{kt}^0) . This inventory has its age updated throughout the planning horizon and it has 149 a straight correspondence to the age of the products when fulfilling demand (ψ_{kt}^a) . 150

The deployment of these two adapted concepts (block planning and simple plant 151 location) results in a base model flexible enough to cope with the basic exigencies 152 of production planning in food industries. 153

The base production planning model of food products (B-PP-FP) reads:

B-PP-FP

$$\max \sum_{k,t,a} p_k d_{kt} \psi_{kt}^a - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt}) - \sum_{k,t,a} h_k (\rho_{kt}^a - d_{kt} \psi_{kt}^a) \quad (1)$$

subject to:

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$$\sum_{a} \psi_{kt}^{a} \leq 1 \quad \forall k \in \mathcal{K}, t \in \mathcal{T}$$
⁽²⁾

$$\rho_{kt}^{a} = \rho_{k,t-1}^{a-1} - d_{k,t-1}\psi_{k,t-1}^{a-1} \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, a \in \mathcal{A} \setminus \{0\}$$
(3)

$$\sum_{l} q_{lkt} = \rho_{kt}^{0} \quad \forall k \in \mathscr{K}, t \in \mathscr{T}$$
(4)

$$p_{lkt} \le y_{ljt} \quad \forall l \in \mathcal{L}, j \in \mathcal{N}, k \in \mathcal{K}_{\mathcal{J}}, t \in \mathcal{T}$$
(5)

$$q_{lkt} \le \frac{C_{lt}}{e_{lk}} p_{lkt} \quad \forall l \in \mathscr{L}, k \in \mathscr{K}, t \in \mathscr{T}$$
(6)

$$\sum_{j} \bar{\tau}_{lj} y_{ljt} + \sum_{k} (\underline{\tau}_{lk} p_{lkt} + e_{lk} q_{lkt}) \le C_{lt} \quad \forall l \in \mathcal{L}, t \in \mathcal{T}$$
(7)

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$$\sum_{k \in \mathscr{K}_{\mathscr{I}}} q_{lkt} \ge m_{lj} y_{ljt} \quad \forall l \in \mathscr{L}, j \in \mathscr{N}, t \in \mathscr{T}$$
(8)

$$\psi_{kt}^{a}, \, \rho_{kt}^{a}, \, q_{lkt} \ge 0; \, p_{lkt}, \, y_{ljt} \in \{0, 1\}$$
(9)

The objective function (1) maximizes the profit of the producer over the planning 157 horizon. Therefore, revenue that comes from sold products is subtracted by setup 158 costs of recipes, setup costs of products, variable production costs and inventory 159 costs. Note that the setup structure considers major and minor setup for the first 160 product to be produced in a given block. For example, in the yoghurt production 161 when changing from one kind of yoghurt to another a major setup might correspond 162 to cleansing the lines and linking the new yoghurt tank, while the minor setup 163 may correspond to setting up the machine to fill the yoghurt in a different type 164 of package. These two operations can seldom be done in parallel.

Constraints (2) forbid the sum of all sold products of different ages to exceed 166 the demand. Constraints (3) establish the inventory balance constraints, ageing the 167 stock throughout the horizon. They state that the inventory of a given age is equal 168 to the inventory in previous period with a younger age subtracted by the amount 169 of products that was sold with the same younger age. Constraints (4) link the 170 production variables to the inventory ones, setting all production in a given period 171 in all lines to the initial stock with age 0. Constraints (5) and (6) ensure that a 172 product can only be produced if both the correspondent block and product are set up, 173 respectively. Limited capacity in the lines is to be reduced by setup times between 174 blocks, setup times between products and also by the time consumed producing 175 products (7). Constraints (8) introduce minimum lot-sizes for each block. 176

Final constraints (9) define the domain of the decision variables.

3 Extending the Constraints of the Base Model

Two main realistic factors may impact the production plans of perishable food 179 products: the fact that inventory that is beyond the expiry date can no longer be sold 180 (product-related), and the fact that customers in face of inventories with different 181 shelf-lives, choose products with the farthest expiry date (customer-related). These issues are addressed in turn by limiting the feasibility domain as follows. 183

3.1 Inventory Expiry Constraints

In order to make sure that no expired products are used to satisfy demand it suffices 185 to redefine the demand fulfillment related constraints dealing with these variables. 186

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The production planning model of food products with inventory expiry 187 constraints (IE-PP-FP) reads: 188

IE-PP-FP

 $\max \sum_{k,t,a} p_k d_{kt} \psi_{kt}^a - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt}) - \sum_{k,t,a} h_k (\rho_{kt}^a - d_{kt} \psi_{kt}^a)$

subject to:

$$\sum_{a \le u_k - 1} \psi_{kt}^a \le 1 \quad \forall k \in \mathscr{K}, t \in \mathscr{T}$$
(10)

$$\rho_{kt}^{a} = \rho_{k,t-1}^{a-1} - d_{k,t-1}\psi_{k,t-1}^{a-1} \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, a \in \mathcal{A} \setminus \{0\} : a \le u_{k}$$
(11)
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(4), (5), (6), (7), and (8)
$$\psi_{kt}^{a}, \rho_{kt}^{a}, q_{lkt} \ge 0; p_{lkt}, y_{ljt} \in \{0, 1\}$$

In constraint (10) we now limit the age of the products used to fulfill demand to be strictly below the product's shelf-life (u_k). Constraint (11) updated the age of the products in stock until products reach their respective shelf-life. In fact, the market conditions can be even more adverse. Retailers usually do not accept products that have already passed one third of their total shelf-life. The remaining constraints are exactly the same as in the base model of Sect. 2.

3.2 Consumer Behaviour Constraints

In a context where the production process is tightened to the downstream supply 200 chain processes satisfying final customers demand, it may be important to better 201 incorporate the instinctive behaviour of consumers. Regarding food products, 202 usually a last-expired-first-out (LEFO) policy is put in practice by customers. This 203 behaviour may guide production plans towards a more just-in-time philosophy in 204 which products' freshness is a priority. 205

It is necessary to add a new decision variable θ_{kt}^a in order to model this behaviour 206 that equals 1, if inventory of product *k* with age *a* is used to satisfy demand in period 207 *t* (0 otherwise). 208

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The production planning model of food products incorporating consumer 209 behaviour (CB-PP-FP) reads: 210

CB-PP-FP

$$\max \sum_{k,t,a} p_k d_{kt} \psi_{kt}^a - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt}) - \sum_{k,t,a} h_k (\rho_{kt}^a - d_{kt} \psi_{kt}^a)$$

subject to:

$$\psi_{kt}^{a} \le \theta_{kt}^{a} \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, a \in \mathcal{A} : a \le u_{k} - 1$$

$$(12)$$

$$d_{a} t^{a-1} \le M(1 - \theta_{a}^{a}) \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, a \in \mathcal{A} \setminus \{0\} : a \le u_{k} - 1$$

$$\varphi_{kt}^{a-1} - d_{kt} \psi_{kt}^{a-1} \le M(1 - \theta_{kt}^{a}) \quad \forall k \in \mathcal{K}, t \in \mathcal{I}, a \in \mathscr{A} \setminus \{0\} : a \le u_k - 1$$

$$(13)$$

(10), (11), (4)(5), (6), (7), and (8)

$$\psi^{a}_{kt}, \rho^{a}_{kt}, q_{lkt} \ge 0; \theta^{a}_{kt}, p_{lkt}, y_{ljt} \in \{0, 1\}$$
(14)

In the previous models, it is assumed that the seller is able to assign optimal 215 inventory quantities of different ages to customers in order to maximize profit. With 216 constraints (12) and (13) this advantage no longer holds as the more instinctive 217 consumer purchasing behaviour of perishable products that will drive customers 218 to pick up products with the highest degree of freshness is mimicked. Thus, 219 constraints (12) turn the value of θ_{kt}^a to 1, whenever inventory of a given product 220 k in period t with age a is used to satisfy demand. The value of this variable θ_{kt}^a 221 is used in constraints (13) to ensure that a fresher inventory can only be used after 222 depleting the older inventory. In these constraints every time inventory of age a 223 from a product k in period t is used (θ_{kt}^a), then either all fresher inventory was used 224 to satisfy demand ($\rho_{kt}^{a-1} - d_{kt}\psi_{kt}^{a-1} = 0$) or there was no such younger inventory 225 ($\rho_{kt}^{a-1} = 0$). Note that parameter M denotes a big number. 226

4 Extending the Objective Function of the Base Model

The most common approach to grasp the perishability phenomena is to penalize 228 the spoiled products with a discard cost in the objective function. This penalty cost 229 makes sense if we acknowledge that products have a limited shelf-life and probably 230 an associated discarding cost. Another approach derives from the awareness of the 231 customers' willingness to pay for fresher products while, simultaneously, the level 232 of information regarding the detailed values of this willingness to pay is low. In 233 this case, a new objective function is added to the one maximizing profit, aiming at 234 maximizing the freshness of the products delivered. 235

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4.1 Discarding Costs in the Objective Function

By incorporating discarding costs we extend the traditional production planning ²³⁷ objective function by incorporating perishability related costs. We define the cost of ²³⁸ spoiled products (\bar{p}_k) as an opportunity cost. This opportunity cost corresponds to ²³⁹ the revenue yielded by the best alternative that could have been produced and sold ²⁴⁰ instead of producing product *k* that got spoiled. However, it may also be regarded, ²⁴¹ in a more tangible manner, as a disposal cost for each unit of perished inventory that ²⁴² has to be properly discarded. ²⁴³

The production planning model of food products including discarding costs 244 (DC-PP-FP) reads: 245

DC-PP-FP

$$\max \sum_{k,t,a} p_k d_{kt} \psi^a_{kt} - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt}) - \sum_{k,t,a} h_k (\rho^a_{kt} - d_{kt} \psi^a_{kt}) - \sum_{k,t,a \ge u_k} \bar{p}_k \rho^a_{kt} \qquad (15)$$

subject to:

(2), (3), (4), (5), (6), (7), and (8) $\psi_{kt}^{a}, \rho_{kt}^{a}, q_{lkt} \ge 0; p_{lkt}, y_{ljt} \in \{0, 1\}$

The only difference to the model presented in Sect. 2 is reflected by the cost of 249 spoilage tracked by the last term of (15). This cost is incurred whenever we hold 250 stock that is beyond the product's shelf-life ($\rho_{kt}^a > 0 : a \ge u_k$). 251

4.2 Measuring Freshness as an Objective Function

In this model, the economic tangible profit is separated from the customer intangible ²⁵³ value of having fresher products available in two distinct objective functions. The ²⁵⁴ main motivation for such splitting comes from the fact that finding the willingness ²⁵⁵ to pay for different customers is rather difficulty and lengthy to grasp in practice. ²⁵⁶ The first objective continues to be the maximization of profit and the second one ²⁵⁷ maximizes the average freshness of delivered products [2]. These two objectives ²⁵⁸ are certainly conflicting since achieving a higher freshness of products delivered ²⁵⁹ has to be done at the expense of more production lots that lead to higher setup costs. ²⁶⁰ Therefore, we acknowledge the complete different nature of the two complementary ²⁶¹

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objectives and the difficulty to attribute different monetary values to different ²⁶² degrees of freshness. As a result, the decision maker/planner will be offered a tradeoff between freshness of delivered products and total profit. This trade-off can be ²⁶³ represented by a set of solutions which do not dominate one another regarding both ²⁶⁵ objectives (non-dominated or Pareto optimal front). We need to define the following ²⁶⁶ additional parameter [d_{kt}] that is the number of non-zero occurrences in the demand ²⁶⁷ matrix. This parameter is useful to have a more straightforward interpretation of the ²⁶⁸ objective function value. ²⁶⁹

The model that accounts for a measure of freshness (MF-PP-FP) reads:

MF-PP-FP

$$\max \sum_{k,t,a} p_k d_{kt} \psi_{kt}^a - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt})$$
(16)
$$\max \frac{1}{[d_{kt}]} \sum_{k,t,a} \frac{u_k - a}{u_k} \psi_{kt}^a$$
(17)

subject to:

(2), (3), (4), (5), (6), (7), and (8)
$$\psi^{a}_{kt}, \rho^{a}_{kt}, q_{lkt} \ge 0; p_{lkt}, y_{lit} \in \{0, 1\}$$

The first objective function (16) maximizes profit in a similarly way of the base 274 model. In the second objective (17) the mean freshness of products to be delivered 275 is maximized. The number of periods before spoilage is estimated by $u_k - a$ and 276 it is then normalized by the estimated shelf-life of the corresponding product. The 277 cardinality of the non-zero demand occurrences is used to normalize this objective 278 function between 0 and 1. This cardinality, for a given input set data, is constant 279 and easily computed. Therefore, a value of 1 means that all products are delivered 280 to customers in their fresher state. 281

This approach for modelling the production planning for food products has 282 an interesting aspect to consider regarding inventory costs. When maximizing 283 freshness in the second objective we are already trying to minimize stocks since 284 we try to produce as late as possible in order to deliver products that were just 285 produced. Therefore, if we had also included inventory costs in the first objective 286 we would be somehow duplicating the inventory carrying cost effect and objective 287 functions (16) and (17) would be too correlated (which must be avoided in multi-288 objective optimization). 289

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5 **Extending the Parameters of the Base Model**

Another form of differentiating the base model of food production planning is by 291 changing or detailing the input parameters, namely: price and demand. The key 292 reasoning is that with more accurate information and more transparency across the 293 supply chain partners, it would be possible to discriminate either price or demand in 294 function of the actual age of the products. 295

5.1 Value of Freshness Parameter

In this model it is assumed that either the retailer or the final customer will be willing 297 to pay a different price for products with different standards of freshness. Therefore, 298 the price parameter is extended to \hat{p}_{k}^{a} , price of product k paid when the product has 299 an age a. 300

The production planning model of food products with different freshness values 301 (VF-PP-FP) reads: 302

VF-PP-FP

$$\max \sum_{k,t,a} \hat{p}_{k}^{a} d_{kt} \psi_{kt}^{a} - \sum_{l,j,t} \bar{s}_{lj} y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt}) - \sum_{k,t,a} h_{k} (\rho_{kt}^{a} - d_{kt} \psi_{kt}^{a}) \quad (18)$$

subject to:

(2), (3), (4), (5), (6), (7), and (8)
$$\psi^{a}_{kt}, \rho^{a}_{kt}, q_{lkt} \ge 0; p_{lkt}, y_{ljt} \in \{0, 1\}$$

The only difference to the model presented in Sect. 2 is reflected in the depen- 306 dency of the revenue to the age of the delivered products. Comparing with objective 307 function (1), objective function (18) has a revenue term that is function of the age 308 of the products sold. Remark that this is a straightforward extension from the base 309 model (Sect. 2), because we have already incorporated a detailed demand fulfillment 310 decision variable (ψ_{kt}^a) tracking the age of the products. 311

5.2**Demand Parameter**

In this model we assume that according to the information about the customer 313 purchasing behaviour, it is possible to determine a parameter d_{kt}^a for the demand for 314

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Fig. 4 Schematic example of the age dependent demand

product *k* with age *a* in period *t*. Furthermore, we assume that the demand decreases 315 with the ageing of the products (Fig. 4). For understanding how this parameter may 316 be generated using empirical data about products and customers' willingness to pay 317 the readers are referred to Amorim et al. [3], Tsiros and Heilman [13]. 318

The production planning model of food products with an extended demand 319 parameter (DP-PP-FP) reads: 320

DP-PP-FP

$$\max \sum_{k,t,a} p_k \, \hat{d}^0_{kt} \, \psi^a_{kt} - \sum_{l,j,t} \bar{s}_{lj} \, y_{ljt} - \sum_{l,k,t} (\underline{s}_{lk} \, p_{lkt} + c_{lk} \, q_{lkt}) - \sum_{k,t,a} h_k \, (\rho^a_{kt} - \hat{d}^0_{kt} \psi^a_{kt}) \quad (19)$$

subject to:

$$\hat{d}^{0}_{kt}\psi^{a}_{kt} \leq \hat{d}^{a}_{kt} \quad \forall k \in \mathscr{K}, t \in \mathscr{T}, a \in \mathscr{A}$$

$$\tag{20}$$

$$\rho_{kt}^{a} = \rho_{k,t-1}^{a-1} - \hat{d}_{k,t-1}^{0} \psi_{k,t-1}^{a-1} \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, a \in \mathscr{A} \setminus \{0\}$$
(21)

(2), (4), (5), (6), (7), and (8)

 $\psi_{kt}^{a}, \, \rho_{kt}^{a}, \, q_{lkt} \geq 0; \, p_{lkt}, \, y_{ljt} \in \{0, 1\}$

The formulation incorporating different demand levels according to the age of 324 the product is very similar to the base model presented in Sect. 2, but in this model 325 the demand parameter is replaced by an extended form that differentiates between 326 products with different ages. Moreover, constraints (20) do not allow the quantity of 327 sold products of a given age to be above the demand curve derived for the respective 328 product (cf. Fig. 4). 329

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6 Illustrative Example

The aim of this illustrative example is to understand the changes in the structure of ³³¹ the production plans when using the different models presented through Sects. 2, 3, ³³² 4, and 5. ³³³

The setting for the illustrative example consists in a production line (L = 1) ³³⁴ that has to produce 2 blocks (N = 2), each with two products (K = 4). For all ³³⁵ products/blocks $e_{lk} = 1$, $m_{lj} = 3$ and $\underline{s}_{lj} = \underline{\tau}_{lj} = 1$. For Block 1 the setup cost (\bar{s}_{lj}) ³³⁶ and the setup time $(\bar{\tau}_{lj})$ is 5 and 1, respectively. For Block 2 $\bar{s}_{lj} = 5$ and $\bar{\tau}_{lj} = 2$. The ³³⁷ considered planning horizon has 4 periods (T = 4) and the capacity C_{lt} equals 35 ³³⁸ for all periods and lines. The remaining parameters are given in Table 1.

We further consider, for the model of Sect. 4.1, that discarding costs \bar{p}_k equal 340 to p_k . In order to obtain one solution for the multi-objective model presented 341 in Sect. 4.2, a weight of 200 was given to the freshness objective in order to 342 have high freshness standards. In general, this is a parameter obtain in pre- 343 computational experiments and it is dependent on the instances. With this weighted 344 linear scalarizing factor, the problem objectives are aggregated in a single one. 345 However, notice that in order to take full advantage of the multi-objective model and 346 obtain the Pareto front a different method, such as the epsilon-constraint approach 347 should be used instead. In the case in which a decreasing value is considered for the 348 price paid for the product throughout its shelf-life (Sect. 5.1), we consider that for 349 products with an age higher than 0, $\hat{p}_k^a = 1$. Finally, for the last model (Sect. 5.2), 350 all products suffer from a 50% rate of decrease in the demand for each period of 351 ageing $(\hat{d}_{kt}^{a+1} = 0.5\hat{d}_{kt}^a)$.

6.1 Results and Discussion

Table 2 shows the results for the key decision variables under analysis q_{lkt} , ρ_{kt}^a , ψ_{kt}^a 354 (production, inventory, demand fulfillment) for all models from Sects. 2, 3, 4, and 355 5. All instances were solved to optimality in less than two seconds by the solver 356 IBM ILOG CPLEX 12.4 and the models were coded in the IBM ILOG OPL IDE. 357 We purposely omitted the objective function values as they are not relevant for our 358 discussion. 359

Table 1	Remaining p	parameters	for the illustrativ	e example

						d_{kt}			
Block	Product	u_k	p_k	C _{lk}	h_k	1	2	3	4
1	1	1	3	1	0.2	5	0	5	5
1	2	1	3	1	0.2	0	10	10	5
2	3	2	4	2	0.1	10	5	0	10
2	4	3	4	2	0.1	5	15	10	5

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Table 2 Results for the decision variables q_{Rr} , ψ_{di}^{a} for all models (Sects. 2, 3, 4, and 5). Values that are the same across all models are in light grey and results that differ between the models (except the base one – B-PP-FP) are in bold. Notice that the relation between the time and age index is respected in this table $(a \in \mathscr{A} = \{a \in \mathbb{Z}_0^+ | a < t - 1\})$

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Overall, results seem to indicate that even for an illustrative example, by 360 incrementally introducing different features and methods for better tackling the food 361 production planning, different solutions are obtained for almost every model tested. 362 The only production plan leading to spoiled products is the base model (B-PP-FP) 363 when products 1 and 2 reach an age of 1 in period 4 ($\rho_{14}^1 = \rho_{24}^1 = 5$). All the 364 other models are able to avoid the expiration of these products due to different 365 reasons. For example, while the model considering inventory expiry (IE-PP-FP) 366 avoids spoilage by the fact that we limit the demand fulfilment to products with 367 a significant remaining shelf-life, the model introducing discarding costs (DC-PP- 368 FP) is able to achieve the same solution by penalizing the occurrence of expired 369 inventory.

One interesting analysis lies on the different solutions found with the inventory 371 expiry model (IE-PP-FP) and the consumer behaviour one (CB-PP-FP). The only 372 difference between these models in the inclusions of constraints (12) and (13) in the 373 CB-PP-FP model, which mimic the fact that customers pick up the fresher available 374 products. For product 4 in period 2 when 20 units are produced in both models 375 $(q_{142} = 20)$, model IE-PP-FP is able to allocate in order to satisfy demand part of the 376 production of period 2 and part of the production of period 1 with age 1 ($\psi_{42}^0 = 73 \%$ 377 and $\psi_{42}^1 = 27\%$). On the contrary, the CB-PP-FP model is forced to satisfy all 378 demand in period 2 with the production executed in the same day ($\psi_{42}^0 = 100\%$ 379 and $\psi_{42}^1 = 0\%$). These differences ultimately lead to the fact that customers in 380 period 3 are penalized in the CB-PP-FP model as they will be satisfied with less 381 fresh products ($\psi_{43}^2 = 40\%$). This fact could potentially lead to lost sales and it 382 reflects the importance of proper inventory control when dealing with perishable 383 products. 384

From the seven models, it is clear that the last three are able to better incorporate ³⁸⁵ the consumer eagerness for fresher products. In particular, the model measuring ³⁸⁶ freshness (MF-PP-FP) and the model having an extended demand parameter (DP- ³⁸⁷ PP-FP) have an equivalent behaviour. Both models incorporate explicitly the ³⁸⁸ importance of satisfying customers with a high degree of freshness. The difference ³⁸⁹ between them relies on the amount and quality of information the decision maker ³⁹⁰ has when setting up the model (less information for the MF-PP-FP and more for the ³⁹¹ DP-PP-FP). ³⁹²

7 Risk-Conscious Planning

In the previous models (Sects. 2, 3, 4, and 5) a major assumption is the deterministic ³⁹⁴ parameter of demand. As seen in the illustrative example (Sect. 6), in this setting ³⁹⁵ spoiled products will only appear in case no perishability considerations are taken ³⁹⁶ into account. This can be done by constraining the domain of the variables used ³⁹⁷ to track both demand fulfillment and inventory levels. However, in this type of ³⁹⁸ industries, producers and retailers struggle with significant amounts of spoiled ³⁹⁹ products. These quantities are tightly correlated to the uncertainty in the forecast of ⁴⁰⁰

demand. Explicitly acknowledging the existence of such uncertainty and adopting 401 a risk conscious planning promise robust and sustainable gains. With this approach 402 the distribution of the gains is sharper and further away from the loss side. This 403 comes at the expense of a decrease in the expected profit. 404

In this section we start by extending the Base model (Sect. 2) in order to cope 405 with an uncertain demand parameter and we then give an example of a risk-averse 406 formulation that tackles explicitly the conditional value-at-risk. The section ends 407 with an extension of the illustrative example of Sect. 6. 408

7.1 **Risk-Neutral Model**

The uncertainty of the demand parameter \tilde{d}_{kt}^v may be modeled though a set of 410 scenarios \mathscr{V} that have a probability of occurrence ϕ_v . In order to incorporate this 411 stochastic parameter into the formulation, it is necessary to determine the moment 412 in time in which demand is unveiled with certainty. In the most common setting, 413 the planner has to decide about the sizing and scheduling of lots in the first-stage 414 and then inventory allocation decisions are done with full knowledge of the demand 415 parameter (second-stage). 416

To model the production planning of perishable foods good in an uncertain 417 setting it is necessary to define the following second-stage decision variables: 418

Second-Stage Decision Variables

 $\tilde{\rho}_{kt}^{av} \geq 0$ initial inventory of product k with age a available at period t in scenario v

 $\tilde{\psi}_{kt}^{av} \geq 0$ fraction of the maximum demand for product k delivered with age a at period t in scenario v

The risk-neutral production planning model of food products (RN-PP-FP) reads: 421

RN-PP-FP

$$\max \sum_{v} \phi_{v} \left[\sum_{k,t,a} p_{k} \, \tilde{d}_{kt}^{v} \, \tilde{\psi}_{kt}^{av} - \sum_{k,t,a} h_{k} \left(\tilde{\rho}_{kt}^{av} - \tilde{d}_{kt}^{v} \, \tilde{\psi}_{kt}^{av} \right) \right] - \sum_{l,j,t} \bar{s}_{lj} \, y_{ljt} \\ - \sum_{l,k,t} \left(\underline{s}_{lk} \, p_{lkt} + c_{lk} \, q_{lkt} \right)$$
(22)

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subject to:

$$\sum_{a} \tilde{\psi}_{kt}^{av} \le 1 \quad \forall k \in \mathcal{K}, t \in \mathcal{T}, v \in \mathcal{V}$$
(23)

$$\tilde{\rho}_{kt}^{av} = \tilde{\rho}_{k,t-1}^{a-1,v} - \tilde{d}_{k,t-1}\tilde{\psi}_{k,t-1}^{a-1,v} \quad \forall k \in \mathscr{K}, t \in \mathscr{T}, a \in \mathscr{A} \setminus \{0\}, v \in \mathscr{V}$$
(24)

$$\sum_{l} q_{lkt} = \tilde{\rho}_{kt}^{0v} \quad \forall k \in \mathscr{K}, t \in \mathscr{T}, v \in \mathscr{V}$$
(25)

(5), (6), (7), and (8)

$$\tilde{\psi}_{kt}^{av}, \, \tilde{\rho}_{kt}^{a}, \, q_{lkt} \ge 0; \, p_{lkt}, \, y_{ljt} \in \{0, 1\}$$
(26)

The objective function (22) maximizes the expected profit of the producer over 425 the planning horizon. In this two-stage stochastic formulation, both revenue and 426 holding costs are now dependent on the scenario realization. The second-stage 427 constraints related to inventory management and demand fulfillment (23), (24), and 428 (25) were changed to incorporate the new stochastic setting. 429

7.2 Risk-Averse Model

In face of uncertainty the planner may take several attitudes in terms of risk. 431 For a risk-conscious attitude it is necessary to introduce a risk measure into the 432 formulation. Recent studies showed that for production planning of perishable 433 food goods the conditional value-at-risk [10, 11], which is very used in portfolio 434 optimization, is a good option as it reduces drastically the amount of expired 435 products at the expense of a small loss on the expected profit [1]. To introduce 436 this risk measure in the formulation we need to further define two decision variables 437 and two parameters α and λ . α controls the confidence interval of the conditional 438 value-at-risk and λ controls the risk-aversion emphasis of the generated plan. 439

Conditional Value-at-Risk Decision Variables

 η value-at-risk

 δ_v auxiliary variable for calculating the conditional value-at-risk

In Fig. 5 a graphical interpretation of this measure is given. Consider *X* to be a 442 random profit distribution, from the figure it is easy to interpret that the conditional 443 value-at-risk (cVaR) is then defined as $\mathbb{E}[X|X \le VaR(X)]$.

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Fig. 5 Graphical interpretation of the conditional value-at-risk measure (Adapted from Sarykalin et al. [12])

The risk-conscious production planning model of food products (RC-PP-FP) 445 reads: 446

RC-PP-FP

$$\max \sum_{v} \phi_{v} \left[\sum_{k,t,a} p_{k} \tilde{d}_{kt}^{v} \tilde{\psi}_{kt}^{av} - \sum_{k,t,a} h_{k} \left(\tilde{\rho}_{kt}^{av} - \tilde{d}_{kt}^{v} \tilde{\psi}_{kt}^{av} \right) \right] - \sum_{l,j,t} \bar{s}_{lj} y_{ljt}$$
$$- \sum_{l,k,t} \left(\underline{s}_{lk} p_{lkt} + c_{lk} q_{lkt} \right) + \lambda (\eta - \frac{1}{1 - \alpha} \sum_{v} \phi_{v} \delta_{v})$$
(27)

subject to:

$$(23), (24), (25), (5), (6), (7), \text{ and } (8)$$

$$\delta_{v} \ge \eta - (\sum_{k,t,a} p_{k} \tilde{d}_{kt}^{v} \tilde{\psi}_{kt}^{av} - \sum_{k,t,a} h_{k} (\tilde{\rho}_{kt}^{av} - \tilde{d}_{kt}^{v} \tilde{\psi}_{kt}^{av})) \quad v \in \mathscr{V}$$

$$(28)$$

$$\tilde{\ell}_{kt}^{av} = \tilde{\ell}_{kt}^{av} = \delta_{k} \ge 0; \quad \tau \in \mathbb{D}, \quad \tau \in \{0, 1\}.$$

(22)

 $(\mathbf{24})$

$$\bar{\psi}_{kt}^{av}, \, \tilde{\rho}_{kt}^{a}, \, q_{lkt}, \, \delta_{v} \ge 0; \, \eta \in \mathbb{R}; \, p_{lkt}, \, y_{ljt} \in \{0, 1\}$$
(29)

The objective function (27) maximizes the expected profit and, simultaneously, 449 it maximizes the conditional value-at-risk with a confidence of α . The second- 450 stage constraints (23), (24), and (25) are the same of the risk-neutral model. A 451 new constraint (28) has to be added to attribute the variable δ_v a value of zero, 452 if scenario v yields a profit higher than η . Otherwise, variable δ_v is given the 453 difference between the value-at-risk η and the corresponding second-stage profit 454 $\sum_{k,t,a} p_k \tilde{d}^v_{kt} \tilde{\psi}^{av}_{kt} - \sum_{k,t,a} h_k (\tilde{\rho}^{av}_{kt} - \tilde{d}^v_{kt} \tilde{\psi}^{av}_{kt}).$ 455

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			Scenario Profit		
		Expected Profit	Low	Medium	High
RN-PP-FP		105.8	0.0	157.0	161.2
RC-PP-FP	λ=4	95.3	37.8	122.8	126.0

 Table 3 Profit values for the Risk-neutral model, and a Risk-averse model

t14.1

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7.3 Extended Illustrative Example

To understand the importance of a risk-conscious production planning of perishable 457 food products let us use the illustrative example presented in Sect. 6. We have 458 extended the data set by distinguishing three possible demand scenarios, all with 459 the same probability of occurrence (0.33). A medium scenario in which the demand 460 is equal to the one presented in Table 1, a low one in which demand is 50% of 461 its expected value and, finally, a high one in which demand is 50% higher than 462 in the medium scenario. Therefore, we use a simplified scenario-tree with only 463 three scenarios. For assessing the impact of uncertainty and understanding the 464 implications of a risk-conscious planning we obtained optimal solution values for 465 three models: (1) the Base model presented in Sect. 2, (2) the Risk-neutral model 466 RN-PP-FP presented in Sect. 7.1, and (3) a Risk-averse model based on RC-PP-FP 467 presented in Sect. 7.2 (setting $\lambda = 4$ and $\alpha = 0.95$). Results for the last two models 468 are presented in Table 3. The Base model (B-PP-FP) has a solution with a profit of 469 157.0. 470

Results indicate that with the stochastic demand parameter the expected profit 471 drops considerably. Notice that demand parameter used in the Base model is 472 the expected value of the uncertain demand parameter (\tilde{d}_{kt}^v) . In the Risk-neutral 473 approach there is one scenario that would result in a profit of 0. This "bad" scenario 474 is mitigated by in the Risk-conscious model that has its worst scenario with a 475 profit of 37.8. This more balanced overall solution with less dispersion of the profit 476 distribution comes at the expense of a slightly lower expected value of profit.

8 Conclusions

In this paper, we have reviewed several ways of integrating different challenges 479 related to exogenous factors (such as customer behaviour and the perishable 480 nature of the products) arising in the production planning of food products. The 481 formulations have the same base model as starting point and we have organised them 482 based on the extensions of the model components required: constraints, objective 483 function and parameters. In particular, we have analysed how to limit the inventory 484 age based on an adapted simple plant location reformulation, how to incorporate the 485

consumer behaviour within the inventory policy, how to include discarding costs in 486 the objective function, how to model customer willingness for fresh products in a 487 multi-objective framework and how to value freshness either in the price or demand 488 parameters. To analyse the implications of each of these "ingredients", an illustrative 489 example is presented and solved, exposing the different solution structures achieved. 490 The differences across the solutions show the importance of choosing an approach 491 suitable to the particular business setting, in order to accommodate the multiple 492 challenges present in these industries. Moreover, acknowledging the perishable 493 nature of the products and evaluating the amount and quality of information at hands 494 may be crucial in lowering disposal costs and achieving higher service levels. There 495 are other ingredients not so related to the perishable nature of food products that 496 are also important in food production planning. For example, Wang et al. [14] deals 497 with the incorporation of batch traceability that is increasingly important with the 498 recent cases of products recall. 499

In the last Section, we analyzed a recent trend in supply chain planning – riskconscious planning. The mitigation of uncertainties in this industries is crucial since their effects are leveraged by the perishable nature of the products. The importance of a risk-averse approach is especially noticeable in terms of avoiding disastrous uncertain outcomes.

Future work should explore these extensions from a computational point of view. 505 Therefore, devising which solution methods are more appropriate for each setting is 506 still a gap to be addressed. 507

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