

1 PAPER

2 Weighted synchronous automata[†]

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Abstract

This paper introduces a class of automata and associated languages, suitable to model a computational paradigm of fuzzy systems, in which both *vagueness* and *simultaneity* are taken as first-class citizens. This requires a weighted semantics for transitions and a precise notion of a synchronous product to enforce the simultaneous occurrence of actions. The usual relationships between automata and languages are revisited in this setting, including a specific Kleene theorem.

Keywords: Weighted automata; regular languages; synchronous languages

8 1. Introduction

9 The notion of an automaton (Kleene 1956), as the *de facto* mathematical abstraction of a com-
10 putational process over a discrete state space, is constantly revisited to capture different sorts of
11 computational behaviours in the most varied contexts, either prescribed in a program or discov-
12 ered in Nature. Already in 1997, Milner (2006) emphasised that *from being a prescription for how*
13 *to do something – in Turing’s terms a ‘list of instructions’, software becomes much more akin to a*
14 *description of behaviour, not only programmed on a computer, but occurring by hap or design inside*
15 *or outside it*. Over time different kinds of automata were proposed *generate* (or *recognise*, depend-
16 ing on the perspective) such behaviours (or the languages that express them). Regular expressions,
17 as a basic notation to express languages and behaviours, were first axiomatised by Kozen (1990) as
18 Kleene algebras, which are basically partially ordered, semirings endowed with a closure operator.
19 Several interpretations and variants of this structure are documented in the literature (Hoare et al.
20 2011; Jipsen and Andrew Moshier 2016; Kozen and Mamouras; Kozen 1997; McIver et al. 2006,
21 2013; Qiao et al. 2008; Thiemann 2016).

22 This paper was born out of a challenge: having previously worked with the Fuzzy Arden
23 Syntax (FAS) (Gomes et al. 2021), a fuzzy, imperative language used for medical diagnosis and
24 prescription of medical procedures, our aim was to introduce a specific kind of automata, and
25 corresponding languages, are able to express the behaviour of the underlying fuzzy systems.

26 Two specific ingredients have to be taken into consideration. The first is *vagueness*, or
27 *uncertainty*, a notion that underlies the interpretation of both variables and predicates in FAS
28 programs. The second is *simultaneity*, i.e. a form of *parallel execution* which is not captured by

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29 non-deterministic interleaving of elementary steps, as in typical models of concurrency. Consider,
 30 for illustration purposes, the following program.

31 **Example 1.1.**

```
32 if (Temperature is in Fever_condition)
33 then medicine:=5 else medicine:=0
```

34 The program adjusts the dose of medicine to be administered to a patient depending on her
 35 temperature. The variable `Fever_condition` is a function assigning, to each real value of the
 36 temperature measured, a value (e.g. within the range $[0, 1]$) to record how close such tem-
 37 perature is of a ‘fever condition’. In a scenario where the predicate `Temperature is in`
 38 `Fever_condition` and its negation have a value greater than 0, let us say, 0.4 and 0.6, respec-
 39 tively, the program executes both the `then` and the `else` blocks, weighted by the value associated
 40 to each of them. In practice, this results in a multiplication of the values taken, in each case, by
 41 variable `medicine`. Intuitively, the values 0.4 and 0.6 mean that `Temperature` has probably not
 42 reached the limit of a fever condition but is close to it.

43 Summing up, the intended semantics of a conditional statement in FAS does not reduce to a
 44 non-deterministic, or even to a probabilistic choice (McIver *et al.* 2013). Instead, it corresponds
 45 to a sort of parallel execution enforcing all branches to run in parallel, with (possibly) different
 46 weights associated to the evaluation of each condition. Therefore, as this small program illustrates,
 47 *vagueness* and *simultaneity* are the two ingredients our framework needs to deal with.

48 *Vagueness* can be captured by a *fuzzy* finite-state automata (FFA), a structure introduced
 49 in the 1960’s in Wee and Fu (1969) to give a formal semantics to uncertainty and vagueness
 50 inherent to several computational systems. Different variants of this idea, e.g. incorporat-
 51 ing fuzziness into either states or transitions, or both, are well documented in the litera-
 52 ture (Doostfateme and Kremer 2005; Li and Pedrycz 2005; Liu *et al.* 2021; Mateescu *et al.* 1995).
 53 The corresponding *fuzzy* languages (Lee and Zadeh 1969; Zadeh 1996) are recognised by this
 54 class of automata only up to a certain membership degree. Applications are transversal to several
 55 domains as reported in Lin and Ying (2002), Mordeson and Malik (2002), Pedrycz and Gacek
 56 (2001), Ying (2002).

57 On the other hand, *simultaneity* was suitably formalised in what Milner called the ‘synchronous
 58 version of CCS’ – the SCCS calculus (Milner 1983), a variant of CCS (Milner 1980) where arbi-
 59 trary actions are allowed to execute *synchronously*. This very same idea of synchronous evolution
 60 appears in the work of C. Prisacariu on synchronous Kleene algebra (Prisacariu 2010). Models for
 61 such structures are given in terms of sets of synchronous strings and finite automata accepting
 62 them. These structures found application, for instance, in variants of deontic logic to formalise
 63 contract languages (Seegerberg 1982; von Wright 1968) and of Hoare logic to reason about parallel
 64 synchronous programs with shared variables (Prisacariu 2010).

65 The aim of this paper is to formalise the behaviour of this class of systems. \mathcal{H} -automata are
 66 introduced as a variant of fuzzy transition automata in the spirit of reference (Mateescu *et al.*
 67 1995), where transitions take ‘truth’ values in a complete Heyting algebra \mathcal{H} , and a suitable
 68 synchronous product construction is defined. The paper proceeds by generalising synchronous
 69 sets (Prisacariu 2010) into a notion of a \mathcal{H} -synchronous language, defined as a word valuation
 70 function over \mathcal{H} . Some preliminary results in this direction appeared in the authors’ conference
 71 paper (Gomes *et al.* 2020). However, the formal framework was now completely redefined in a
 72 very general sense – note, for example, that the need for explicitly introducing \mathcal{H} -valued guards
 73 in the language, as suggested in that preliminary work, becomes redundant, i.e. implicit in the
 74 relevant mathematical structure and, thus, in the proposed language semantics.

75 As a main result it is shown that, for any complete Heyting algebra \mathcal{H} ,
 76 \mathcal{H} -synchronous languages equipped with suitable language operators, as proposed here,

77 defines a synchronous Kleene algebra. Moreover, its actions can generate a \mathcal{H} -automaton accept-
 78 ing precisely the \mathcal{H} -synchronous language that constitutes its interpretation. As in the classical,
 79 well-known case, a regular expression can be obtained from a \mathcal{H} -automaton by a standard state
 80 elimination procedure (Hopcroft et al. 2003). The procedure results in a \mathcal{H} -automaton with a
 81 single transition from the initial to the final state, labelled by an action α whose interpretation is
 82 precisely the language recognised by that \mathcal{H} -automaton.

83 This paper is organised as follows. The remaining of this section sums up related work and
 84 some preliminaries to the paper's contribution. Section 2 introduces \mathcal{H} -synchronous languages
 85 and defines a number of operators over them, proving that, in this way \mathcal{H} -synchronous languages
 86 forms a synchronous Kleene algebra. Section 3 studies \mathcal{H} -automata, including their synchronous
 87 product. A few examples of FAS programs involving conditionals are interpreted in this frame-
 88 work. Then, a Kleene theorem for \mathcal{H} -automata and \mathcal{H} -synchronous languages is proved in
 89 Section 4. Finally, Section 5 concludes and enumerates some topics for future research.

90 1.1 Related work

91 The construction of a finite fuzzy automata with membership degrees taken in a lattice-ordered
 92 monoid \mathcal{L} is studied in Li and Pedrycz (2005) in a context analogous to the one considered here,
 93 based on the concept of \mathcal{L} -fuzzy regular expression. Those are defined as regular expressions from
 94 an alphabet X with a scalar $\lambda \in \mathcal{L}$ multiplication, which resorts to the monoid multiplication. It
 95 is precisely this scalar that attributes the weight to a transition in the automaton. In our approach,
 96 on the other hand, automata are built using standard regular expressions instead of fuzzy regular
 97 expressions. Regular expressions are then interpreted as some sort of weighted languages (i.e.
 98 functions with values on a complete Heyting algebra) accepted by an automaton with weighted
 99 transitions.

100 Most of the results presented in the context of fuzzy languages are constructed using either the
 101 real interval $[0, 1]$ or a generic residuated lattice to model the (possible) many valued membership
 102 values. Such is the case of reference (Mateescu et al. 1995). However, one of the main results of this
 103 paper, Theorem 1, relies on properties provided by a specific characterisation of the underlying lat-
 104 tice structure. In particular, the operator ‘;’ has to be idempotent and commutative. The definition
 105 a \mathcal{H} -automaton proposed here differs from the one in Mateescu et al. (1995) with respect to the
 106 underlying semantic structure, which is assumed to be as a complete Heyting algebra.

107 Probabilistic automata (Rabin 1963), another approach to handle uncertainty, weight transi- Q3
 108 tion by elements of a probability distribution. An equivalent to Kleene's theorem for these family
 109 of automata is presented by Bollig et al. (2012), considering (probabilistic) strings with probabilis-
 110 tic choice, guarded choice, concatenation and the star operator. Extensive surveys on this class
 111 of automata are documented in Vidal et al. (2005a,b). In the approach proposed here, however,
 112 *uncertainty* can be measured in an arbitrary, either discrete or continuous, domain, depending on
 113 the relevant application scenario. This is captured by a complete Heyting algebra introduced as a
 114 parameter in the model.

115 Figure 1 summarises some systems from the literature, highlighting the difference of the
 116 approach taken in this paper.

117 Moreover, as we summarised above, the notion of weight can take different meanings. Figure 2
 118 summarises some of these different approaches.

119 1.2 Preliminaries

120 The notion of a synchronous Kleene algebra (SKA) plays in the automata construction introduced
 121 by Prisacariu (2010) a role similar to the one played by Kleene algebras in the classical case (Broda
 122 et al. 2013). Actually, SKA:

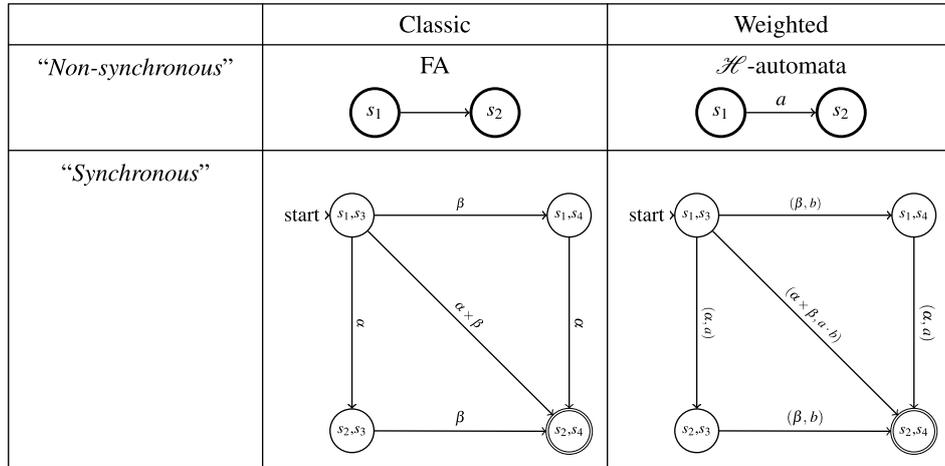


Figure 1. Simple representation of different classes of automata: finite state automata, their version with weights introduced in this paper (\mathcal{H} -automata) and the synchronous product (non-weighted Prisacariu 2010 and weighted).

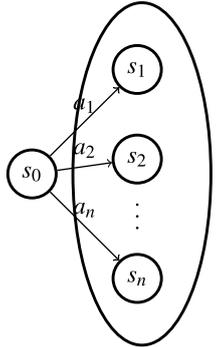
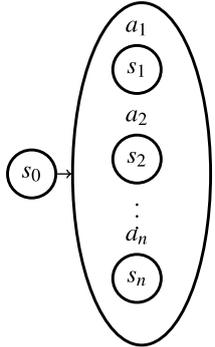
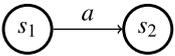
	Probabilistic automata (Rabin 1963)	\mathcal{L} -fuzzy finite automata (Li and Pedrycz 2005)	\mathcal{H} -automata
			
Transitions	valued by elements of a probabilistic distribution D	classic with \mathcal{L} -valued weights in states	valued by elements of \mathcal{H}
Languages	regular languages with probabilistic choice $+_a$	functions from strings to \mathcal{L}	sets of strings with \mathcal{H} -valued atomic actions

Figure 2. Taxonomy of related work. Values a, a_1, \dots, a_n represent probabilities or weights.

- 123 • extends Kleene algebra with a synchronous operator to model synchronous execution of
- 124 actions;
- 125 • has an interpretation over synchronous languages, the equivalent of regular languages to
- 126 include actions corresponding to the synchronous execution of other actions;
- 127 • induce the construction of a class of finite automata, which accept the same languages that
- 128 defines the interpretation of the SKA actions.

129 The relevant definitions are recalled below.

130 **Definition 1.** (Kleene algebra). A Kleene algebra $(A, +, \cdot, *, \mathbf{0}, \mathbf{1})$ is an idempotent semiring with
 131 a unary operator $*$ satisfying axioms (1)–(13) in Table 1. Partial order \leq is induced by $+$ as
 132 $\alpha \leq \beta \Leftrightarrow \alpha + \beta = \beta$.

133 Well-known examples of Kleene algebras include the algebra of binary relations over a set, the
 134 set of all languages over an alphabet, and the $(\min, +)$ -algebra, also known as the tropical algebra,
 135 defined over the reals with an additional $+\infty$ constant, as

$$\mathbf{R} = (\mathbb{R}_0^+ \cup +\infty, \min, +, *, +\infty, 0)$$

136 Extending this definition with a multiplication \times to capture the synchronous execution of
 137 actions¹ leads to the notion of a *synchronous Kleene algebra (SKA)*, introduced in Prisacariu
 138 (2010).

Definition 2. (SKA). Let B be a set of labels. A SKA is a Kleene algebra extended with an operator
 \times i.e. a tuple

$$\mathbf{S} = (A, B, +, \cdot, \times, *, \mathbf{0}, \mathbf{1})$$

139 where $B \subset A$, satisfying the axioms in Table 1.

$\alpha + (\beta + \gamma) = (\alpha + \beta) + \gamma$	(1)	$\alpha \cdot \gamma \leq \gamma \Rightarrow \alpha^* \cdot \gamma \leq \gamma$	(12)
$\alpha + \beta = \beta + \alpha$	(2)	$\gamma \cdot \alpha \leq \gamma \Rightarrow \gamma \cdot \alpha^* \leq \gamma$	(13)
$\alpha + \alpha = \alpha$	(3)	$\alpha \times (\beta \times \gamma) = (\alpha \times \beta) \times \gamma$	(14)
$\alpha + \mathbf{0} = \mathbf{0} + \alpha = \alpha$	(4)	$\alpha \times \beta = \beta \times \alpha$	(15)
$\alpha \cdot (\beta \cdot \gamma) = (\alpha \cdot \beta) \cdot \gamma$	(5)	$\alpha \times \mathbf{1} = \mathbf{1} \times \alpha = \alpha$	(16)
$\alpha \cdot \mathbf{1} = \mathbf{1} \cdot \alpha = \alpha$	(6)	$\alpha \times \mathbf{0} = \mathbf{0} \times \alpha = \mathbf{0}$	(17)
$\alpha \cdot (\beta + \gamma) = (\alpha \cdot \beta) + (\alpha \cdot \gamma)$	(7)	$a \times a = a, a \in B$	(18)
$(\alpha + \beta) \cdot \gamma = (\alpha \cdot \gamma) + (\beta \cdot \gamma)$	(8)	$\alpha \times (\beta + \gamma) = (\alpha \times \beta) + (\alpha \times \gamma)$	(19)
$\alpha \cdot \mathbf{0} = \mathbf{0} \cdot \alpha = \mathbf{0}$	(9)	$(\alpha + \beta) \times \gamma = (\alpha \times \gamma) + (\beta \times \gamma)$	(20)
$\mathbf{1} + (\alpha \cdot \alpha^*) = \alpha^*$	(10)	$(\alpha \times \alpha) \times (\beta \times \beta) = (\alpha \times \beta) \times (\alpha \times \beta)$, where	(21)
$\mathbf{1} + (\alpha^* \cdot \alpha) = \alpha^*$	(11)	$\alpha \times, \beta \times \in B^\times$, with B^\times the \times -closure of B .	

Table 1. Axiomatisation of a SKA (based on Prisacariu 2010)

140 Following a common practice, we write ab , rather than $a \cdot b$, for $a, b \in B$. Note that axiom (18)
 141 applies only to elements of B , instead of any arbitrary action A . This comes from the fact that
 142 such a property, being intuitive for atomic actions, is not so, or even desirable, for an arbitrary
 143 action in A . Consider, for example, action $(a + b) \times (a + b)$, whose execution may result in $a \times b$
 144 by choosing a from the first entity and b from the second. However, by the axiomatisation above,
 145 we have

$$\begin{aligned}
 & (a + b) \times (a + b) \\
 146 & = \quad \{ (19) \} \\
 & \quad (a + b) \times a + (a + b) \times b \\
 & = \quad \{ (20) \} \\
 & \quad (a \times a) + (b \times a) + (a \times b) + (b \times b)
 \end{aligned}$$

$$\begin{aligned}
147 \quad &= \{ (15) \} \\
&(a \times a) + (a \times b) + (a \times b) + (b \times b) \\
&= \{ (3) \text{ and } (18) \} \\
&a + (a \times b) + b
\end{aligned}$$

148 Moreover, axiom (21) provides an exchange like rule to describe interaction between elements
149 in B^\times and A . The restriction to actions in B^\times relates to the synchrony model, describing the
150 parallelism of sequences of actions by concatenating small synchronous steps.

We will call by *synchronous regular expressions* the terms of a SKAs, i.e., the terms given the grammar

$$\alpha ::= a \mid \mathbf{0} \mid \mathbf{1} \mid \alpha + \alpha \mid \alpha \cdot \alpha \mid \alpha \times \alpha \mid \alpha^*$$

151 where a is a *atomic action*, constituting the set B . Actions $\alpha_\times, \beta_\times$ are built only with operator
152 ‘ \times ’ from B , constituting the set B^\times (e.g. $a, a \times b \in B^\times$ but $a + b, a \times b + c, \mathbf{0}, \mathbf{1} \notin B^\times$). The set of
153 synchronous regular expressions will be denoted by Sreg .

154 If synchronous execution of actions is captured as above, vagueness, on the other hand, requires
155 the consideration of weighted transitions forming a complete Heyting algebra.

156 **Definition 3.** (Complete Heyting algebra). *A Heyting algebra is a bounded distributive lattice*

$$\mathcal{H} = (H, \vee, \wedge, \mathbf{0}, \mathbf{1}, \rightarrow)$$

157 with join ‘ \vee ’ and meet ‘ \wedge ’ operators, least ‘ $\mathbf{0}$ ’ and greatest ‘ $\mathbf{1}$ ’ elements, equipped with a binary
158 operator ‘ \rightarrow ’ that is right adjoint to ‘ \wedge ’. Some axioms are listed in Table 2.

$$a \wedge b = b \wedge a \tag{22}$$

$$a \wedge a = a \tag{23}$$

$$a \vee (a \wedge b) = a \tag{24}$$

$$a \wedge b \leq c \Leftrightarrow b \leq a \rightarrow c \tag{25}$$

Table 2. Part of the axiomatisation of a Heyting algebra

159 \mathcal{H} is a complete Heyting algebra (CHA) iff it is complete as a lattice, therefore entailing the
160 existence of arbitrary suprema. The usual precedence of the operators, with ‘ $*$ ’ having the highest
161 precedence, then ‘ \cdot ’, ‘ \times ’, and finally ‘ $+$ ’, will be assumed.

162 Let us briefly revisit some properties of this structure that will be later used in proofs.
163 Completeness ensures that all suprema exist when characterising operators ‘ \cdot ’, ‘ \times ’ and ‘ $*$ ’ on
164 \mathcal{H} -synchronous languages as (possible) infinite sums. Let us denote by \bigvee, \bigwedge the distributed ver-
165 sions of the associative operators ‘ \vee ’ and ‘ \wedge ’, respectively, and by I a (possible infinite) index set.
166 Axiom (25) ensures that every suprema distributes, on both sides, over arbitrary infima, i.e.

$$a \wedge \left(\bigvee_{i \in I} a_i \right) = \bigvee_{i \in I} (a \wedge a_i) \tag{26}$$

$$\left(\bigvee_{i \in I} a_i \right) \wedge a = \bigvee_{i \in I} (a_i \wedge a) \tag{27}$$

167 Instances of a complete Heyting algebra are enumerated in the following examples.

Example 1.2. (2- the Boolean algebra). A first example is the well-known binary structure

$$\mathbf{2} = (\{\top, \perp\}, \vee, \wedge, \perp, \top, \rightarrow)$$

168 with the standard interpretation of Boolean connectives.

169 **Example 1.3.** A second example is the three-valued Gödel chain, which introduces an explicit
170 denotation u for ‘unknown’ (or ‘undefined’). $\mathbf{3} = (\{\top, u, \perp\}, \vee, \wedge, \perp, \top, \rightarrow)$ where

\vee	\perp	u	\top	\wedge	\perp	u	\top	\rightarrow	\perp	u	\top
\perp	\perp	u	\top	\perp	\perp	\perp	\perp	\perp	\top	\top	\top
u	u	u	\top	u	\perp	u	u	u	\perp	\top	\top
\top	\top	\top	\top	\top	\perp	u	\top	\top	\perp	u	\top

171 **Example 1.4.** (Gödel algebra). Another example is given by the standard Gödel algebra
172 $\mathbf{G} = ([0, 1], \max, \min, 0, 1, \rightarrow)$ where

$$x \rightarrow y = \begin{cases} 1, & \text{if } x \leq y \\ y, & \text{if } y < x \end{cases}$$

173 2. \mathcal{H} -Synchronous Languages

174 In order to capture both *synchronous execution* and *vagueness* in transitions, their interpre-
175 tation is made over synchronous languages with embedded weights. The latter are taken, as
176 explained above, from a complete Heyting algebra \mathcal{H} . In a sense, this generalises the work
177 of Prisacariu (2010) which considers non-weighted, but synchronous languages. A number of
178 operators over these languages, referred to as \mathcal{H} -synchronous languages, are introduced below,
179 structuring this domain as a SKA, parametric on the set of weights.

180 **Definition 4.** (\mathcal{H} -synchronous languages). Let B be a set of symbols and \mathcal{H} a complete Heyting
181 algebra over a carrier H . \mathcal{H} -synchronous actions are pairs associating a non-empty set of sym-
182 bols in B to a weight in H . Formally, $\Sigma = \mathcal{P}_{ne}(B) \times H \setminus \{\mathbf{0}\}$, where $\mathcal{P}_{ne}(X)$ denotes the non-empty
183 powerset of X . For each action, functions $b : \Sigma \rightarrow \mathcal{P}_{ne}(B)$ and $h : \Sigma \rightarrow H \setminus \{\mathbf{0}\}$, denote the cor-
184 responding projections. \mathcal{H} -synchronous words are elements of Σ^* . \mathcal{H} -synchronous languages are
185 sets of such words, i.e. elements of $\mathcal{P}(\Sigma^*)$.

The weight of a word is computed by

$$hs : \Sigma^* \rightarrow H, \quad hs(u) = \bigwedge_{x \leftarrow u} h(x)$$

186 Clearly, $hs(\varepsilon) = \mathbf{1}$, for ε the empty string.

As an illustration, consider a finite set of labels $B = \{a, b\}$ and take the Gödel algebra \mathbf{G} , from
Example 1.4, as a domain for weights. Thus, representing a sequence by the juxtaposition of its
elements, $hs(\{a\}, 0.6)(\{a, b\}, 0.5) = 0.6 \wedge 0.5 = 0.5$. Thus, one may turn a language $\mathcal{L} \in \mathcal{P}(\Sigma^*)$
into a function of synchronous words to weights through a translation function

$$t : \mathcal{P}(\Sigma^*) \rightarrow H^{\mathcal{P}(B)^*}$$

187 such that

$$t(\emptyset) = ()$$

$$t(\mathcal{L}) = (\pi_1^*(w) \mapsto hs(w))_{w \in \mathcal{L}}$$

188 Of course, t is not injective, thus two characterisations of a language, i.e. as an element of $\mathcal{P}(\Sigma^*)$ Q4
 189 or of $H^{\mathcal{P}(B)^*}$, are not isomorphic. Function hs is particularly relevant to state, as we will do later,
 190 that an automata recognises a word w if it does so with a weight equal or bigger than $hs(w)$.

191 The standard operators from regular language theory can be defined over
 192 \mathcal{H} -synchronous languages, as follows.

193 **Definition 5.** The following operations are defined over \mathcal{H} -synchronous languages $\mathcal{L}, \mathcal{L}_1, \mathcal{L}_2$, for
 194 any complete Heyting algebra \mathcal{H} :

- 195 - $\emptyset = \emptyset$ (the empty language)
- 196 - $\mathbf{1} = \{\varepsilon\}$ (the language containing only the empty string)
- 197 - $\mathcal{L}_1 + \mathcal{L}_2 = \mathcal{L}_1 \cup \mathcal{L}_2$
- 198 - $\mathcal{L}_1 \cdot \mathcal{L}_2 = \{uv \mid u \in \mathcal{L}_1, v \in \mathcal{L}_2\}$
- 199 - $\mathcal{L}_1 \times \mathcal{L}_2 = \{u \times v \mid u \in \mathcal{L}_1, v \in \mathcal{L}_2\}$, where $u \times v$ is defined by
 - 200 - $u \times \varepsilon = u = \varepsilon \times u$
 - 201 - $u \times v = (b(x) \cup b(y), h(x) \wedge h(y))(u' \times v')$ where $u = xu'$ and $v = yv'$.
- 202 - \mathcal{L}^* is the least fixed point of equation $X = \mathbf{1} + \mathcal{L} \cdot X$.

203 With respect to the product of languages, note that $\{a, b\} \in \mathcal{L}_1 \times \mathcal{L}_2$ may correspond to any of
 204 the following situations: $\{a\} \in \mathcal{L}_1$ and $\{b\} \in \mathcal{L}_2$, $\{b\} \in \mathcal{L}_1$ and $\{a\} \in \mathcal{L}_2$, or, finally, $\{a, b\}$ belongs
 205 just to one of the languages, and ε to the other. Note also that if $a \in \mathcal{L}_1$ and $bc \in \mathcal{L}_2$, then $\{a, b\}c \in$
 206 $\mathcal{L}_1 \times \mathcal{L}_2$.

207 **Definition 6.** (Atomic languages). Let B be a set of symbols and \mathcal{H} a complete Heyting algebra over
 208 a carrier H and $\Sigma = \mathcal{P}_{ne}(B) \times H \setminus \{\mathbf{0}\}$ a set of synchronous actions. The set of atomic actions of Σ
 209 is given by $\Sigma_0 = \{a \in \Sigma \mid |b(a)| = 1\}$. For any atomic action $a \in \Sigma_0$, the language $\mathcal{L}_a = \{a\}$ is called
 210 atomic language. We denote by \mathcal{B}_Σ the class of atomic languages of Σ and by $\mathcal{B}_\Sigma^\times$ the \times -closure of
 211 \mathcal{B} . We use also \mathcal{L}_Σ to denote the class of the languages of Σ .

212 **Theorem 1.** Let B be a set of symbols and \mathcal{H} a complete Heyting algebra over a carrier H and
 213 $\Sigma = \mathcal{P}_{ne}(B) \times H \setminus \{\mathbf{0}\}$ a set of synchronous actions. The structure

$$L = (\mathcal{L}_\Sigma, \mathcal{B}_\Sigma, +, \cdot, \times, *, \emptyset, \mathbf{1})$$

214 defines a SKA.

215 *Proof.* We detail the verification of axioms (1), (13), (20) and (18) making repeated use of
 216 Definition 5. The remaining cases follow a similar argument. For axiom (1) observe:

$$\begin{aligned} & w \in \mathcal{L}_1 \cdot (\mathcal{L}_2 \cdot \mathcal{L}_3) \\ \Leftrightarrow & w = u \cdot v \text{ such that } u \in \mathcal{L}_1 \text{ and } v \in \mathcal{L}_2 \cdot \mathcal{L}_3 \\ \Leftrightarrow & w = u \cdot v \text{ such that } u \in \mathcal{L}_1 \text{ and } v = s \cdot t \text{ such that } s \in \mathcal{L}_2 \text{ and } t \in \mathcal{L}_3 \\ \Leftrightarrow & w = u \cdot s \cdot t \text{ such that } u \cdot s \in \mathcal{L}_1 \cdot \mathcal{L}_2 \text{ and } t \in \mathcal{L}_3 \\ \Leftrightarrow & w \in (\mathcal{L}_1 \cdot \mathcal{L}_2) \cdot \mathcal{L}_3 \end{aligned}$$

217 Regarding axiom (18), consider the atomic language \mathcal{L}_a . We have

$$\begin{aligned} & w \in \mathcal{L}_a \times \mathcal{L}_a \\ \Leftrightarrow & w = a \times a \text{ such that } a \in \mathcal{L}_a \\ \Leftrightarrow & w = (b(a) \cup b(a), h(a) \wedge h(a)) \text{ such that } a \in \mathcal{L}_a \end{aligned}$$

$$\begin{aligned} &\Leftrightarrow w = a \text{ such that } a \in \mathcal{L}_a \\ &\Leftrightarrow w \in \mathcal{L}_a \end{aligned}$$

218 For axiom (20),

$$\begin{aligned} &w \in (\mathcal{L}_1 + \mathcal{L}_2) \times \mathcal{L}_3 \\ &\Leftrightarrow u \in (\mathcal{L}_1 + \mathcal{L}_2) \text{ and } v \in \mathcal{L}_3 \text{ for some } u \text{ and } v \text{ such that } w = u \times v \\ &\Leftrightarrow u \in (\mathcal{L}_1 \cup \mathcal{L}_2) \text{ and } v \in \mathcal{L}_3 \text{ for some } u \text{ and } v \text{ such that } w = u \times v \\ &\Leftrightarrow u \in \mathcal{L}_1 \text{ or } u \in \mathcal{L}_2, \text{ and } v \in \mathcal{L}_3, \text{ for some } u \text{ and } v \text{ such that } w = u \times v \\ &\Leftrightarrow w \in \mathcal{L}_1 \times \mathcal{L}_3 \text{ or } w \in \mathcal{L}_2 \times \mathcal{L}_3 \\ &\Leftrightarrow w \in (\mathcal{L}_1 \times \mathcal{L}_3) + (\mathcal{L}_2 \times \mathcal{L}_3) \end{aligned}$$

219 For axiom (21), consider the Σ -languages $\mathcal{L}_1^\times, \mathcal{L}_2^\times \in \mathcal{B}^\times$. Then,

$$\begin{aligned} &w \in (\mathcal{L}_1^\times \cdot \mathcal{L}_1) \times (\mathcal{L}_2^\times \cdot \mathcal{L}_2) \\ &\Leftrightarrow w = (x \cdot u) \times (y \cdot v) \text{ such that } x \in \mathcal{L}_1^\times, u \in \mathcal{L}_1, y \in \mathcal{L}_2^\times, v \in \mathcal{L}_2 \\ &\Leftrightarrow (b(x) \cup b(y), h(x) \wedge h(y)) \cdot (u \times v) \text{ such that } x \in \mathcal{L}_1^\times, u \in \mathcal{L}_1, y \in \mathcal{L}_2^\times, v \in \mathcal{L}_2 \\ &\Leftrightarrow (x \times y) \cdot (u \times v) \text{ such that } (x \times y) \in \mathcal{L}_1^\times \times \mathcal{L}_2^\times, u \times v \in \mathcal{L}_1 \times \mathcal{L}_2 \\ &\Leftrightarrow w \in (\mathcal{L}_1^\times \times \mathcal{L}_2^\times) \cdot (\mathcal{L}_1 \times \mathcal{L}_2) \end{aligned}$$

220

□

221 Similarly to the homomorphism used to interpret Sreg as synchronous sets (Prisacariu 2010),
222 we define a map to interpret actions of $\alpha \in \text{Sreg}$ as \mathcal{H} -synchronous languages.

223 **Definition 7.** (Sreg-interpretation). *The function $I : \text{Sreg} \rightarrow \mathcal{P}(\Sigma^*)$, called a Sreg-interpretation,*
224 *is defined as follows:*

$$\begin{aligned} 225 &I(a) = \mathcal{L}_a, a \in B \times H \\ 226 &I(\mathbf{0}) = \emptyset \\ 227 &I(\mathbf{1}) = \chi \\ 228 &I(\alpha + \beta) = I(\alpha) \cup I(\beta) \\ 229 &I(\alpha \cdot \beta) = I(\alpha) \cdot I(\beta) \\ 230 &I(\alpha \times \beta) = I(\alpha) \times I(\beta) \\ 231 &I(\alpha^*) = I(\alpha)^* \end{aligned}$$

232 3. \mathcal{H} -Automata

233 This section presents the automata construction for \mathcal{H} -synchronous languages. First we define
234 a class of automata on top of a complete Heyting algebra \mathcal{H} , referred as \mathcal{H} -automata. An
235 appropriate notion of a synchronous product for these automata is then presented.

236 **Definition 8.** (\mathcal{H} -Automata). *Let \mathcal{H} be a complete Heyting algebra and B a set of symbols. A*
237 *\mathcal{H} -automaton is a tuple*

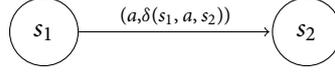
$$\mathcal{M} = (S, \Sigma, s_0, F, \delta)$$

238 where:

- 239 • S is a finite set of states;
- 240 • $\Sigma = \mathcal{P}_{ne}(B) \times H$ is the input alphabet;

- 241 • $s_0 \in S$ is the initial state;
- 242 • $F \subseteq S$ is the set of final states;
- 243 • $\delta : S \times \Sigma \times S \rightarrow H$ is the transition function.

244 Intuitively, $\delta(s_1, x, s_2)$, for $x \in \Sigma$, can be interpreted as the truth degree of ‘input x causing a tran-
 245 sition from s_1 to s_2 ’. In a graphical representation of a \mathcal{H} -automaton, the weight of a transition
 246 from s_1 to s_2 caused by an action a is represented explicitly as follows:



The transition function can be inductively extended to sequences Σ^* by defining $\delta^* : S \times \Sigma^* \times S \rightarrow H$ such that, for any $s_1, s_2 \in S$,

$$\delta^*(s_1, \varepsilon, s_2) = \begin{cases} \mathbf{1} & \text{if } s_1 = s_2 \\ \mathbf{0} & \text{otherwise} \end{cases}$$

247 and, for any $s_1, s_2 \in S$, $w \in \Sigma^*$ and $x \in \Sigma$,

$$\delta^*(s_1, xw, s_2) = \bigvee_{s' \in S} (\delta(s_1, x, s') \wedge \delta^*(s', w, s_2))$$

248 Clearly, for any states $s_1, s_2 \in X$ and any word $w \in \Sigma^*$, $\delta^*(s_1, w, s_2)$ can be interpreted as the truth
 249 degree of ‘word w causes a transition from s_1 to s_2 ’.

250 A recognising function for a particular automaton \mathcal{M} succeeds in recognising a word if, for each
 251 label $x \in \Sigma$ appearing in the word, the weight associated to the corresponding transition $\delta(s_1, x, s_2)$
 252 is such that $h(x) \leq \delta(s_1, x, s_2)$. Formally,

253 **Definition 9.** (Recognising function). Let \mathcal{H} be a complete Heyting algebra and
 254 $\mathcal{M} = (S, \Sigma, s_0, F, \delta)$ a \mathcal{H} -automata. The recognising function for \mathcal{M} , $\rho_{\mathcal{M}} : S \times \Sigma^* \times S \rightarrow H$, is
 255 recursively defined by

$$\rho_{\mathcal{M}}(s_1, xw, s_2) = \begin{cases} \delta(s_1, x, s') \wedge \rho_{\mathcal{M}}(s', w, s_2) & \text{if } h(x) \leq \delta(s_1, x, s') \\ \mathbf{0} & \text{otherwise} \end{cases}$$

and

$$\rho_{\mathcal{M}}(s_1, \varepsilon, s_2) = \begin{cases} \mathbf{1} & \text{if } s_1 = s_2 \\ \mathbf{0} & \text{otherwise} \end{cases}$$

256 **Definition 10.** Let \mathcal{H} be a complete Heyting algebra, $\mathcal{M} = (S, \Sigma, s_0, F, \delta)$ be an \mathcal{H} -automaton,
 257 and $\rho_{\mathcal{M}}$ a recognising function for \mathcal{M} . The \mathcal{H} -synchronous language recognised by \mathcal{M} is defined
 258 as follows:

$$\mathcal{L}(\mathcal{M}) = \{w \in \Sigma^* \mid \rho_{\mathcal{M}}(s_0, w, s) > \mathbf{0} \text{ for some } s \in F\}$$

259 **Theorem 2.** Let \mathcal{H} be a complete Heyting algebra, $\mathcal{M} = (S, \Sigma, s_0, F, \delta)$ be an \mathcal{H} -automaton, and
 260 $\rho_{\mathcal{M}}$ a recognising function for \mathcal{M} and $w \in \Sigma^*$. Then,

$$w \in \mathcal{L}(\mathcal{M}) \text{ iff } \rho_{\mathcal{M}}(s_0, w, s) \geq hs(w)$$

261 *Proof.* First observe that from the definitions of $\rho_{\mathcal{M}}$ and hs , for any $s, s' \in S$ and $w \in \Sigma^*$, either
 262 $\rho_{\mathcal{M}}(s, w, s') = \mathbf{0}$ or $\rho_{\mathcal{M}}(s, w, s') \geq hs(w)$. For the converse direction, since $\rho_{\mathcal{M}}(s, w, s') \geq hs(w)$, we
 263 have $\rho_{\mathcal{M}}(s, w, s') \geq \mathbf{0}$ and hence $w \in \mathcal{L}(\mathcal{M})$. \square

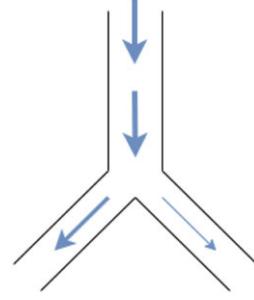


Figure 3. Conditional in FAS, illustrated by a liquid flowing through a ‘Y-shaped’ pipe.

264 We end this section defining and exemplifying a notion of synchronous product of
 265 \mathcal{H} -automata, which corresponds to the automata counterpart to synchronous composition in
 266 Sreg. It is based on the parallel product of labelled transition systems with shared actions.
 267 Formally,

268 **Definition 11.** (Synchronous product of \mathcal{H} -automata). Let $\mathcal{M}_\alpha = (S^\alpha, \Sigma^\alpha, s_0^\alpha, F^\alpha, \delta^\alpha)$ and $\mathcal{M}_\beta =$
 269 $(S^\beta, \Sigma^\beta, s_0^\beta, F^\beta, \delta^\beta)$ be two \mathcal{H} -automata. Let $\Sigma^{\alpha \times \beta} = \Sigma^\alpha \cup \Sigma^\beta \cup (\Sigma^\alpha \times \Sigma^\beta)$, with

$$\Sigma^\alpha \times \Sigma^\beta = \{a \times b \mid a \in \Sigma^\alpha, b \in \Sigma^\beta\},$$

270 The synchronous product of \mathcal{M}_α and \mathcal{M}_β is the \mathcal{H} -automaton

$$\mathcal{M}_{\alpha \times \beta} = (S^\alpha \times S^\beta, \Sigma^{\alpha \times \beta}, (s_0^\alpha, s_0^\beta), F^\alpha \times F^\beta, \delta^{\alpha \times \beta})$$

271 whose transition function

$$\delta^{\alpha \times \beta} : (S^\alpha \times S^\beta) \times \Sigma^{\alpha \times \beta} \times (S^\alpha \times S^\beta) \rightarrow H$$

272 is defined by, for any $p \in \Sigma^{\alpha \times \beta}$,

$$\delta^{\alpha \times \beta}((s^\alpha, s^\beta), p, (t^\alpha, t^\beta)) = \begin{cases} \delta^\alpha(s^\alpha, p, t^\alpha) & \text{if } p \in \Sigma^\alpha \setminus \Sigma^\beta \text{ and } s^\beta = t^\beta \\ \delta^\beta(s^\beta, p, t^\beta) & \text{if } p \in \Sigma^\beta \setminus \Sigma^\alpha \text{ and } s^\alpha = t^\alpha \\ \bigvee_{\substack{a, b \\ p = a \times b}} (\delta^\alpha(s^\alpha, a, t^\alpha) \wedge \delta^\beta(s^\beta, b, t^\beta)) & \text{otherwise} \end{cases}$$

273 As discussed in the Introduction, \mathcal{H} -automata provide a suitable semantic structure for FAS
 274 programs. Let us illustrate such a potential through the discussion of two concrete examples.

275 **Example 3.1.** Our first example, already mentioned in the introduction as Example 1.1, is that
 276 of a conditional in FAS which involves the simultaneous execution of its branches. An intuitive
 277 metaphor to this behaviour is represented as a pipe as depicted in Figure 3. The liquid, repre-
 278 sented by blue arrows, reaches a point where it flows through both channels in parallel (capturing
 279 simultaneity), with different volumes going through each channel, represented by the different
 280 thicknesses of arrows (representing different truth degrees modelling vagueness).

281 The execution of this program, which involves the multiplication of the values assigned to
 282 variable *medicine* in different branches, may lead to two distinct outcomes:

- 283 (A) The branches remain separated, and further instructions are executed in parallel. The
 284 information from different branches is taken into account by the user;
 285 (B) The information is combined, which results in a single (crisp) output.

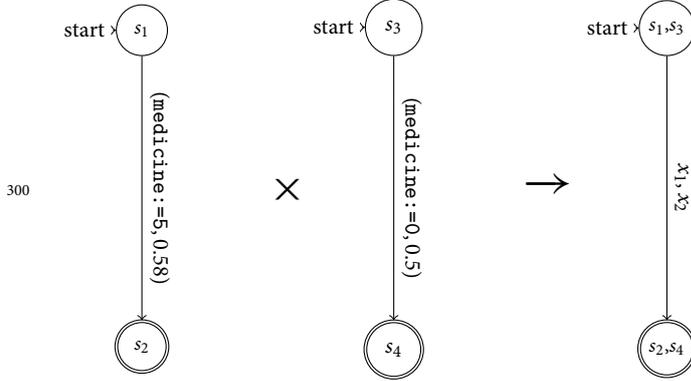
286 Option (B) enforce the consolidation of multiple variable values, which is achieved through
 287 instruction `aggregate`, as in the program:

```
288 if (Temperature is in Fever_condition)
289 then medicine:=5 else medicine:=0
290 aggregate;
291
```

292 This behaviour can be modelled by the synchronous product of the automata, assuming, for
 293 illustration purposes, that the weight of each branch are 0.58 and 0.50, respectively. We also
 294 assume that weights are taken from a Gödel algebra (Example 1.4).



297 Since we are assuming that the truth degrees associated to the evaluation of both branches
 298 are strictly positive, actions `medicine:=5` and `medicine:=0` run in parallel. Formally, the two
 299 automata are combined through ‘ \times ’ giving rise to



301 where $x_1 = (\{\text{medicine}:=5, \text{medicine}:=0\}, \delta((s_1, s_3), \{\text{medicine}:=0, \text{medicine}:=5\}))$ and $x_2 =$
 302 (s_2, s_4)

303 The truth degree associated to aggregated variable `medicine`, after execution depends
 304 on the truth degrees of both branches of the conditional, which corresponds to the
 305 second projection of the actions $(\text{medicine}:=5, \delta^{\text{medicine}:=5}(s_1, \text{medicine}:=5, s_2))$ and
 306 $(\text{medicine}:=0, \delta^{\text{medicine}:=0}(s_3, \text{medicine}:=0, s_4))$. Choosing the minimum function as the
 307 aggregation operator, leads to the following computation:

$$\begin{aligned} & \delta((s_1, s_3), \{\text{medicine}:=5, \text{medicine}:=0\}, (s_2, s_4)) \\ &= (\delta^{\text{medicine}:=5}(s_1, \text{medicine}:=5, s_2) \wedge \delta^{\text{medicine}:=0}(s_3, \text{medicine}:=0, s_4)) \\ &= \min\{0.58, 0.5\} \\ &= 0.5 \end{aligned}$$

308 **Example 3.2.** As a second example consider an excerpt of a FAS program representing a control
 309 system intended to adjust the peak inspiratory pressure (PIP) of a patient depending on her levels
 310 of O_2 and CO_2 , after a cardiac surgery de Bruin *et al.* (2018) .

```
311
312 if (O2 is in O2_normal) and (CO2 is in CO2_very_high)
313 then PIP:=5
314 elseif (O2 is in O2_low) and (CO2 is in CO2_very_high)
315 then PIP:=2
```

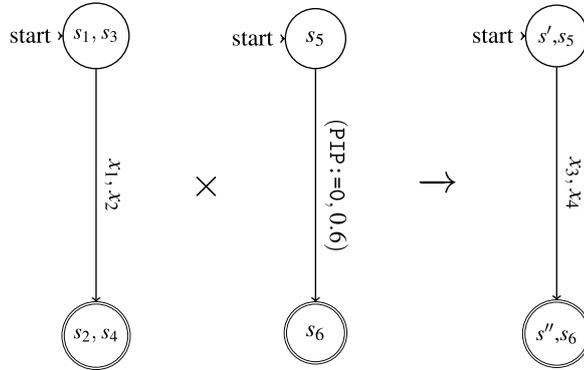


Figure 4. The synchronous product interpreting the FAS conditional.

```

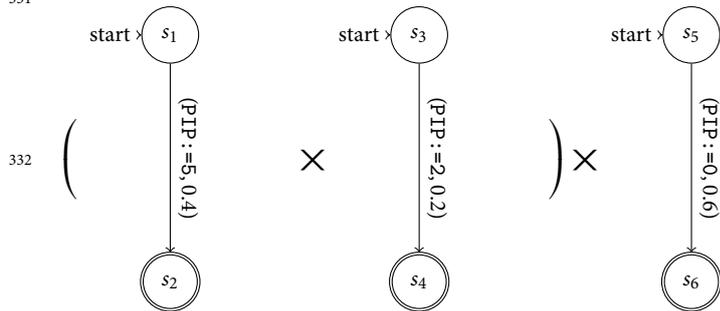
316 if (O2 is in O2_low) and (CO2 is in CO2_high)
317 then PIP:=0
318 aggregate;

```

319
 320 The set of labels in this example is $B = \{\text{PIP}:=5, \text{PIP}:=2, \text{PIP}:=0\}$. Suppose that the truth
 321 degrees of the predicates in each of the branches of the conditional are 0.4, 0.2 and 0.6, respec-
 322 tively, and again assume the Gödel algebra as the domain for weights. The three branches of the
 323 conditional are modelled by the automata below



327 Again, the values of the three predicates are strictly positive and thus the three branches of
 328 the conditional are executed in parallel, corresponding to action $\text{PIP}:=5 \times \text{PIP}:=2 \times \text{PIP}:=0$.
 329 Operator '×' being associative, such behaviour is modelled by the synchronous product of the
 330 three automata above, yielding



333 An intermediate step is represented in Figure 4, with $s' = (s_1, s_3)$, $s'' = (s_2, s_4)$, and (x_1, x_2)
 334 abbreviating $(\{\text{PIP}:=5, \text{PIP}:=2\}, \delta^{\text{PIP}:=5 \times \text{PIP}:=2}((s_1, s_3), \{\text{PIP}:=5, \text{PIP}:=2\}, (s_2, s_4)))$. Similarly,
 335 (x_3, x_4) abbreviates

336
 337 $(\{\text{PIP}:=5, \text{PIP}:=2, \text{PIP}:=0\}, \delta^{\text{PIP}:=5 \times \text{PIP}:=2 \times \text{PIP}:=0}((s', s_5), \{\text{PIP}:=5, \text{PIP}:=2, \text{PIP}:=0\}, (s'', s_6)))$
 338

339 The truth degree corresponding to the combined values taken by variable PIP depends
 340 on three other truth degrees: the second projections of $(PIP:=5, \delta^{PIP:=5}(s_1, PIP:=5, s_2))$,
 341 $(PIP:=2, \delta^{PIP:=2}(s_3, PIP:=2, s_4))$ and $(PIP:=0, \delta^{PIP:=0}(s_5, PIP:=0, s_6))$. It is computed as fol-
 342 lows:

$$\begin{aligned} & \delta^{PIP:=5 \times PIP:=2 \times PIP:=0}((s_1, s_3), \{PIP:=5, PIP:=2, PIP:=0\}, (s'', s_6)) \\ &= (\delta^{PIP:=5}(s_1, PIP:=5, s_2) \wedge \delta^{PIP:=2}(s_3, PIP:=2, s_4) \wedge \delta^{PIP:=0}(s_5, PIP:=0, s_6)) \\ &= \min\{0.4, 0.2, 0.6\} \\ &= 0.2 \end{aligned}$$

343 4. A Kleene Theorem for \mathcal{H} -Synchronous Languages

344 This section establishes a Kleene theorem for \mathcal{H} -automata and \mathcal{H} -synchronous languages. To
 345 proceed in such a direction, however, entails the need for showing that, as it happens in the classic
 346 case, the introduction of non-determinism and transitions labelled by the empty string does not
 347 compromise the expressiveness of finite \mathcal{H} -automata. Such is the aim of the following subsection.

348 4.1 \mathcal{H} -Automata with ε -moves

349 In standard finite automata theory, it is well-known that the introduction of non-determinism and
 350 the presence of ε -moves, i.e. spontaneous transitions labelled by the empty word, do not change
 351 the expressiveness of finite automata, since given a non-deterministic automaton with ε -moves,
 352 there is a standard procedure to build an equally finite and deterministic automaton recognising
 353 exactly the same language (see e.g. Hopcroft and Ullman 1979).

354 This subsection develops an analogous result for \mathcal{H} -automata. Firstly, we notice that the
 355 non-determinism is inherent to the very definition of \mathcal{H} -automata. For example, the non-
 356 deterministic transition $\delta(s, a) = \{w, v\}$ can be represented in a \mathcal{H} -automaton by $\delta(s, a, w) = 1$
 357 and $\delta(s, a, v) = 1$. Of course, it is also easy to characterise the class of finite deterministic automata
 358 as the subclass of \mathcal{H} -automata such that, for each $s, v, w \in S$ and for any symbol a , if $\delta(s, a, v) =$
 359 $1 = \delta(s, a, w)$ then $v = w$. This clarified, let us consider the effect of ε -moves.

360 **Definition 12.** (\mathcal{H} -Automata with ε -moves). *Let \mathcal{H} be a complete Heyting algebra and B a set of*
 361 *symbols. A \mathcal{H} -automata with ε -moves, $\varepsilon\mathcal{H}$ -automaton for short, is a tuple*

$$\mathcal{E} = (S, \Gamma, s_0, F, \delta)$$

362 *where*

- 363 • S is a finite set of states;
- 364 • $\Gamma \subseteq \mathcal{P}(B) \times H$ such that, for any $a \in \Gamma$, if $b(a) = \emptyset$, $h(a) = 1$ (by a slight abuse of notation,
 365 the empty set of symbols will be represented by ε , originating transitions $(\varepsilon, 1)$);
- 366 • $s_0 \in S$ is the initial state;
- 367 • $F \subseteq S$ is the set of final states;
- 368 • $\delta : S \times \Gamma \times S \rightarrow H$ is the transition function such that
 - 369 – for any $s \in S$, $\delta(s, \varepsilon, s) = 1$
 - 370 – for any $s, s' \in S$, $\delta(s, \varepsilon, s') = 1$ or $\delta(s, \varepsilon, s') = 0$.

371 **Definition 13.** *The language recognised by an $\varepsilon\mathcal{H}$ -automaton $\mathcal{E} = (S, \Gamma, s_0, F, \delta)$ is given by*

$$\mathcal{L}^\varepsilon(\mathcal{E}) = \{w \in (\Gamma \setminus \{(\varepsilon, 1)\})^* \mid \rho^\varepsilon(s_0, w, s) > 0, \text{ for some } s \in F\} \quad (28)$$

372 where

$$\rho^\varepsilon(s_1, xw, s_2) = \begin{cases} \delta^\varepsilon(s_1, x, s') \wedge \rho^\varepsilon(s', w, s_2) & \text{if } h(x) \leq \delta^\varepsilon(s_1, x, s') \\ \mathbf{0} & \text{otherwise} \end{cases} \quad (29)$$

373

$$\rho^\varepsilon(s_1, \varepsilon, s_2) = \begin{cases} \mathbf{1} & \text{if } s_1 = s_2 \\ \mathbf{0} & \text{otherwise} \end{cases} \quad (30)$$

374 with

$$\delta^\varepsilon(s, a, v) = \bigvee_{s_1, s_2 \in S} (\delta^*(s, \varepsilon^*, s_1) \wedge \delta(s_1, a, s_2) \wedge \delta^*(s_2, \varepsilon^*, v)) \quad (31)$$

375 for any $a \in \Gamma \setminus \{(\varepsilon, 1)\}$.

376 **Definition 14.** Let $\mathcal{E} = (S, \Gamma, s_0, F, \delta)$, be a $\varepsilon\mathcal{H}$ -automaton with $\mathcal{E} \subseteq \mathcal{P}(B) \times H$. The ε -closure of
377 \mathcal{E} is the \mathcal{H} -automaton

$$\hat{\mathcal{E}} = (\hat{S}, \Sigma, \hat{s}_0, \hat{F}, \hat{\delta}) \quad (32)$$

378 where

- 379 • $\hat{S} = \{\hat{v} \mid v \in S\}$ where $\hat{v} = \{w \mid \delta^*(v, \varepsilon, w) = 1\}$
- 380 • $\Sigma = \Gamma \setminus \{(\varepsilon, 1)\}$
- 381 • $\hat{F} = \{P \in \hat{S} \mid P \cap F \neq \emptyset\}$
- 382 • for any $\hat{s}, \hat{v} \in \hat{S}$ and $a \in \Sigma$, $\hat{\delta}(\hat{s}, a, \hat{v}) = \bigvee_{s \in \hat{s}, v \in \hat{v}} \delta^\varepsilon(s, a, v)$, where

$$\delta^\varepsilon(s, a, v) = \bigvee_{s_1, s_2 \in S} (\delta^*(s, \varepsilon^*, s_1) \wedge \delta(s_1, a, s_2) \wedge \delta^*(s_2, \varepsilon^*, v))$$

383 **Theorem 3.** Let $\mathcal{E} = (S, \Gamma, s_0, F, \delta)$, be a $\varepsilon - \mathcal{H}$ -automaton. Then

$$\mathcal{L}^\varepsilon(\mathcal{E}) = \mathcal{L}(\hat{\mathcal{E}}) \quad (33)$$

384 *Proof.* First, observe that, for any $a \in \Gamma \setminus \{(\varepsilon, 1)\}$ and for all $s, v \in S$,

$$\hat{\delta}(\hat{s}, a, \hat{v}) \geq h(a) \Leftrightarrow \delta^\varepsilon(s, a, v) \geq h(a) \quad (34)$$

385 since

$$\begin{aligned} & \hat{\delta}(\hat{s}, a, \hat{v}) \geq h(a) \\ \Leftrightarrow & \quad \{\hat{\delta} \text{ defn.}\} \\ & \bigvee_{s \in \hat{s}, v \in \hat{v}} \delta^\varepsilon(s, a, v) \geq h(a) \\ \Leftrightarrow & \quad \{\delta^\varepsilon \text{ defn.}\} \\ & \bigvee_{s \in \hat{s}, v \in \hat{v}} \left(\bigvee_{s_1, s_2 \in S} (\delta^*(s, \varepsilon^*, s_1) \wedge \delta(s_1, a, s_2) \wedge \delta^*(s_2, \varepsilon^*, v)) \right) \geq h(a) \\ \Leftrightarrow & \quad \{\hat{s} \text{ defn.}\} \\ & \bigvee_{s_1, s_2 \in S} (\delta^*(s, \varepsilon^*, s) \wedge \delta^*(s, \varepsilon^*, s_1) \wedge \delta(s_1, a, s_2) \wedge \delta^*(s_2, \varepsilon^*, v) \wedge \delta^*(s_2, \varepsilon^*, v)) \geq h(a) \\ \Leftrightarrow & \quad \{\delta^* \text{ defn.}\} \end{aligned}$$

$$\begin{aligned}
& \bigvee_{s_1, s_2 \in S} (\delta^*(s, \varepsilon^*, s_1) \wedge \delta(s_1, a, s_2) \wedge \delta^*(s_2, \varepsilon^*, v)) \geq h(a) \\
& \Leftrightarrow \quad \{ \delta^\varepsilon \text{ defn.} \} \\
& \delta^\varepsilon(s, a, v) \geq h(a)
\end{aligned}$$

386 Then, the result follows by induction on the structure of words. For a basic word $a \in \Gamma \setminus \{(\varepsilon, 1)\}$,

$$\begin{aligned}
& a \in \mathcal{L}^\varepsilon(\mathcal{E}) \\
& \Leftrightarrow \quad \{ (28) \} \\
& \rho^\varepsilon(s_0, a, s) > 0, s \in F \\
& \Leftrightarrow \quad \{ (29) \} \\
& \delta^\varepsilon(s_0, a, s) \geq h(a), s \in F \\
& \Leftrightarrow \quad \{ (34) \} \\
& \hat{\delta}(\hat{s}_0, a, \hat{s}) \geq h(a), s \in \hat{F} \\
& \Leftrightarrow \quad \{ (29) \} \\
& \rho_{\hat{\mathcal{E}}}(\hat{s}_0, a, \hat{s}) > 0, \hat{s} \in \hat{F} \\
& \Leftrightarrow \quad \{ (28) \} \\
& a \in \mathcal{L}(\hat{\mathcal{E}})
\end{aligned}$$

387 For composed words $aw \in (\Gamma \setminus \{(\varepsilon, 1)\})^*$,

$$\begin{aligned}
& aw \in \mathcal{L}^\varepsilon(\mathcal{E}) \\
& \Leftrightarrow \quad \{ (28) \} \\
& \rho^\varepsilon(s_0, aw, s) > 0, s \in F \\
& \Leftrightarrow \quad \{ (29) \} \\
& \delta^\varepsilon(s_0, a, s') \geq h(a) \text{ and } \rho^\varepsilon(s', w, s) > 0, s \in F \\
& \Leftrightarrow \quad \{ (34) + \text{I.H. } (\rho^\varepsilon(s', w, s) > 0 \Leftrightarrow w \in \mathcal{L}^\varepsilon(\mathcal{E})) \text{ and } \rho_{\hat{\mathcal{E}}}(\hat{s}_0, aw, \hat{s}) > 0 \Leftrightarrow w \in \mathcal{L}(\hat{\mathcal{E}})) \} \\
& \hat{\delta}(\hat{s}_0, a, \hat{s}') \geq h(a) \text{ and } \rho_{\hat{\mathcal{E}}}(\hat{s}', w, \hat{s}_f) > 0, \hat{s} \in \hat{F} \\
& \Leftrightarrow \quad \{ (29) \} \\
& \rho_{\hat{\mathcal{E}}}(\hat{s}_0, aw, \hat{s}) > 0, \hat{s} \in \hat{F} \\
& \Leftrightarrow \quad \{ (28) \} \\
& aw \in \mathcal{L}(\hat{\mathcal{E}})
\end{aligned}$$

388

□

389 4.2 The theorem

390 The setting is now ready to establish a Kleene theorem for \mathcal{H} -automata and \mathcal{H} -synchronous
 391 languages. Thus, for any synchronous regular expression $\alpha \in \text{Sreg}$, we will provide a method to

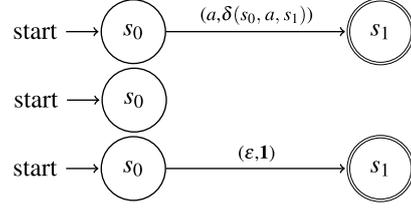


Figure 5. Automata representing actions $a \in \Sigma$, $\mathbf{0}$ and $\mathbf{1}$.

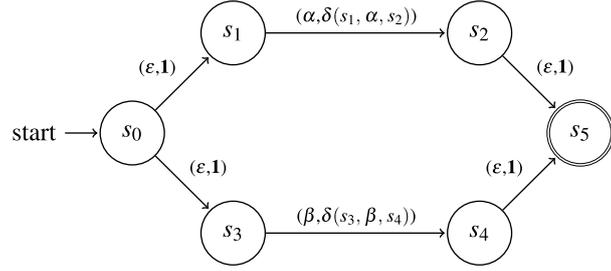


Figure 6. Automaton representing expression $\alpha + \beta$.

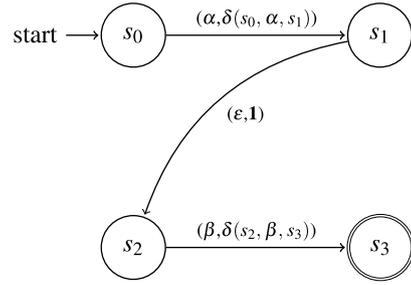


Figure 7. Automaton representing expression $\alpha \cdot \beta$.

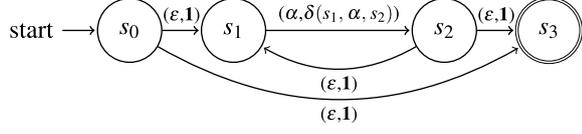
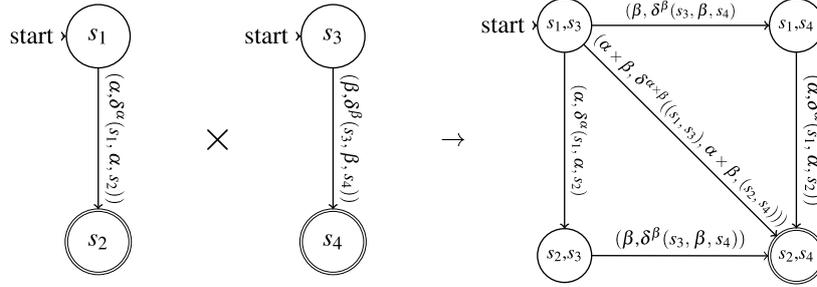
392 build a $\varepsilon\mathcal{H}$ -automaton (translatable to a \mathcal{H} -automaton, as discussed above) \mathcal{M}_α such that $I(\alpha) =$
 393 $\mathcal{L}(\mathcal{M}_\alpha)$.

394 For regular expressions built from atomic actions $a \in \Sigma = \mathcal{P}_{ne}(B) \times H$ without resorting to
 395 the synchronous product operator, the construction follows the classical recipe, as presented e.g.
 396 in Hopcroft and Ullman (1979). This is then extended to synchronous regular expressions, by
 397 generalising a construction in Prisacariu (2010) for the synchronous operator ‘ \times ’.

398 **Theorem 4.** For any $\alpha \in \text{Sreg}$, there exists a \mathcal{H} -automaton \mathcal{M}_α such that

$$I(\alpha) = \mathcal{L}(\mathcal{M}_\alpha)$$

399 *Proof.* The automata corresponding to $a \in \Sigma$, $\mathbf{0}$ and $\mathbf{1}$, denoted, respectively, by \mathcal{M}_a , $\mathcal{M}_\mathbf{0}$ and
 400 $\mathcal{M}_\mathbf{1}$, are depicted in Figure 5. From Definitions 10 and 7, observe that $I(a) = \mathcal{L}_a = \mathcal{L}\mathcal{M}_a$,
 401 $I(\mathbf{0}) = \{\} = \emptyset = \mathcal{L}\mathcal{M}_\mathbf{0}$ and that $I(\mathbf{1}) = \{\varepsilon\} = \mathcal{L}\mathcal{M}_\mathbf{1}$. Then, assuming there exist automata for arbitrary
 402 regular actions α and β , we inductively build an $\varepsilon\mathcal{H}$ -automaton for Sreg expressions
 403 $\alpha + \beta$, $\alpha \cdot \beta$ and α^* . The resulting automata, denoted by $\varepsilon\mathcal{H}$ -automata $\mathcal{E}_{\alpha+\beta}$, $\mathcal{E}_{\alpha \cdot \beta}$, \mathcal{E}_{α^*}
 404 and $\mathcal{E}_{\alpha \times \beta}$, are depicted in Figures 6, 7, 8 and 9, respectively. Clearly, Definition 13 entails
 405 $I(\alpha + \beta) = \mathcal{L}^\varepsilon(\mathcal{E}_{\alpha+\beta})$, $I(\alpha \cdot \beta) = \mathcal{L}^\varepsilon(\mathcal{E}_{\alpha \cdot \beta})$, $I(\alpha^*) = \mathcal{L}^\varepsilon(\mathcal{E}_{\alpha^*})$ and $I(\alpha \times \beta) = \mathcal{L}^\varepsilon(\mathcal{E}_{\alpha \times \beta})$. Then,
 406 by Theorem 3, we conclude that $I(\alpha + \beta) = \mathcal{L}(\hat{\mathcal{E}}_{\alpha+\beta})$, $I(\alpha \cdot \beta) = \mathcal{L}(\hat{\mathcal{E}}_{\alpha \cdot \beta})$, $I(\alpha^*) = \mathcal{L}(\hat{\mathcal{E}}_{\alpha^*})$ and
 407 $I(\alpha \times \beta) = \mathcal{L}(\hat{\mathcal{E}}_{\alpha \times \beta})$. \square

Figure 8. Automaton representing expression α^* .Figure 9. Automaton representing the expression $\alpha \times \beta$.

5. Conclusions

The paper introduced a new class of automata, and corresponding languages, able to capture both *vagueness*, through transitions weighted over a complete Heyting algebra, and *synchronous execution*, through a specific product operator. The work was motivated by the quest for a suitable demantic structure for FAS programs.

To model other situations, for example, in face of a requirement to compute the number of steps involved in an execution, or the resources consumed by a computational process, exploring other structures to parametrise the construction would be a possibility. The tropical semiring

$$R = (\mathbb{R}_+ \cup \{\infty\}, \min, +, \infty, 0, \rightarrow)$$

with $x \rightarrow y = \max\{y - x, 0\}$, $\forall x, y \in \mathbb{R}_+ \cup \{\infty\}$ would be worth to consider, although it fails idempotency and, therefore Theorem 1.

Finally, a detailed comparison with other possible semantic structures is in order. Probabilistic concurrent Kleene algebra (PCKA), introduced in McIver et al. (2013), is an obvious choice. Such an approach embodies two distinct operators: the concurrency operator \parallel , from concurrent Kleene algebra of Hoare et al. (2011), to describe the parallel execution of two crisp actions, and a probabilistic choice operator \oplus , to capture uncertainty in the execution of actions.

For reasoning about concurrent programs with some form of uncertainty, PCKA can model Jones's rely/guarantee style calculus with probabilistic behaviour, resorting to a probabilistic event structure semantics (McIver et al. 2016). On the other hand, SKA encodes reasoning in the style of Qwicki and Gries Owicki and Gries (1976) calculus. A possible direction for future work will investigate whether and how this can be extended to the weighted case.

Conflicts of interest

The authors declare none.

Note

1 Following Prisacariu (2010), the symbol ' \times ' stands for the synchronous product; any possible confusion with the same symbol used for Cartesian product is disambiguated by context.

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